

High Accuracy Power Analysis. Anywhere, Anytime.



Upgrade New current sensors

Engineered for more accurate power measurement

Improved frequency bandwidth and accuracy







High Accuracy and Mobility. A New Value for Power Analysis.

The first-generation Power Analyzer 3390 debuted in 2009 with a collection of the latest measurement technologies packed into a compact design.

Pair with Hioki current sensors and take them anywhere to immediately make highly accurate measurements.

This was the unique value of the 3390.

Now, Hioki has enhanced this value while refining the measurement technology even further.

Proper accuracy and bandwidth to precisely measure inverter output.

Phase shift function for the exact measurement of high frequency, low power factor power.

A broad current sensor lineup that expands the range of measurement possibilities.

Refinements that empower you to conduct precise power analysis in any situation.



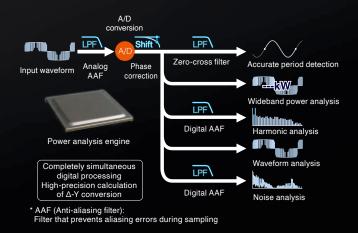
Complete Pursuit of Measurement Accuracy and High Frequency Characteristics

The PW3390 delivers 4 input channels and ±0.04% basic accuracy for power - the top instrument in its class. Achieve more precise measurements of the power and efficiency of high efficiency equipment used in power electronics. Further, a 200 kHz measurement band and flat amplitude and phase characteristics up to high frequencies enable the precise measurement of power at top frequency levels and low power factor.



Power Analysis Engine That Achieves High-Speed Simultaneous Calculation on 5 Systems

Precisely capture input waveforms with 500 kS/s high-speed sampling and a high resolution 16-bit A/D converter. The power analysis engine performs independent digital processing for 5 systems: period detection, wideband power analysis, harmonic analysis, waveform analysis, and noise analysis. High-speed simultaneous calculation processing enables both precise measurements and a 50 ms data refresh rate.



Current Sensors for the Thorough Pursuit of High Accuracy. Achieve Superior Accuracy for High-Frequency, Low Power Factor Power.

High Accuracy Pass-Through Sensor

Pass-through sensors deliver accuracy, broad-band performance, and stability. Measure currents of up to 1000 A with a high degree of accuracy across a broad range of operating temperatures.



High Accuracy Clamp Sensor

Clamp for quick and easy connections. Conduct extremely accurate measurements of large currents to a maximum of 1000 A over a wide operating temperature range.



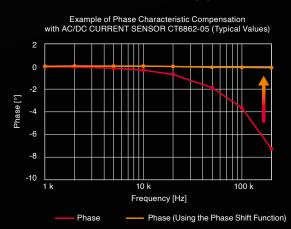
Newly developed DCCT method delivers expansive measurement range and superior measurement accuracy at a rating of 50 A.





Built-in Current Sensor Phase Shift Function

Equipped with new virtual oversampling technology. Achieve phase shift equivalent to 200 MS/s while maintaining a high speed of 500 kS/s, as well as a high resolution of 16 bits. Set and correct the phase error of the current sensor at a resolution of 0.01°. Use of the phase shift function results in a dramatic reduction of measurement error. This allows the measurement of high-frequency, low-power factor power included in the switching frequency of inverter output, which is difficult to measure with conventional equipment.



 Virtual oversampling:
 Technology that uses a sampling frequency several hundred times higher than the actual sampling frequency to perform virtual deskewing





In the Laboratory or in the Field

Take Highly Accurate Measurements Even in Tough Temperature Conditions

Severe temperature environments, such as engine rooms with intense temperature changes and constant temperature rooms, can hinder high accuracy measurements. Hioki provides a lineup of high-accuracy through-type and high-accuracy clamp-type current sensors with excellent temperature characteristics and wide operating temperature ranges.

The PW3390 can operate from a low temperature environment of -10°C to a high temperature of 40°C, allowing you to take it to measure in various environments.



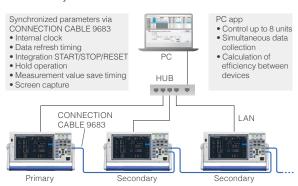
Max. 6000 A Measurement on 50 Hz/60 Hz Lines

The CT7040 AC FLEXIBLE CURRENT SENSOR series can measure commercial power lines up to 6000 A, including solar power conditioner output. Even thick cables can be wired easily among crowded wiring or in narrow locations.



Acquire Data from up to 8 Synchronized Units (32 Channels)

When you connect CONNECTION CABLE 9683 to multiple PW3390 units, the control signals and internal clocks synchronize. From the primary unit, you can control the measurement timing on the PW3390 units that are set as secondaries. With interval measurement, you can save synchronized measurement data to a CF card or a PC to achieve simultaneous measurements across a larger number of systems.



Achieve High Accuracy Measurement Even in the Field

Dramatically compact and light-weight form factor achieved by concentrating the calculation functions in the power analysis engine. Highly accurate measurements normally achieved in the laboratory are now also possible in the field.



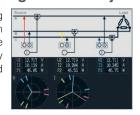
External Power Supply Not Needed for Sensor Connections

Power can be supplied to the current sensor from the main unit, so there is no need to provide a separate external power supply for the current sensor. Connected sensors are recognized automatically, for reliable and quick measurements.



Wiring Displays and Quick Setup Lets You Begin Measuring Immediately

Perform wiring while checking wiring diagrams and vectors on the screen. Optimum settings are performed automatically simply by selecting a connection and using the quick setup function.



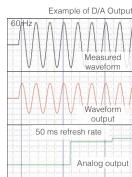
Extensive Interface for Linking with External Devices

Wide variety of built-in interfaces, including LAN, USB (communication, memory), CF cards, RS-232C, synchronization control, and external control.

D/A output* delivers analog output at 50 ms for up to 16 parameters. The voltage and current waveform** for each channel can also be output.







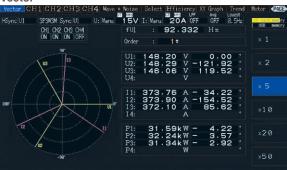
- * Built-in for PW3390-02 and PW3390-03
- ** During waveform output, accurate reproduction is possible at an output of 500 kS/s and with a sine wave up to 20 kHz.

Switch Screens with a Single Touch, **Accessing a Variety of Power Analysis Methods**

The power analysis engine allows the simultaneous, parallel calculation of all parameters. Access a variety of analysis methods simply by pressing the page keys to switch screens.

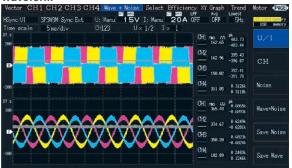


Vector



Confirm the voltage/current/power/phase angle for each harmonic order on a vector graph and as numerical values

Waveform



voltage/current waveforms for 4 channels at a high speed of 500 kS/s or a maximum length of 5 seconds. Waveform data can be saved.

Harmonics Graph



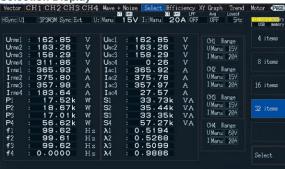
Display harmonics up to the 100th order for voltage/current/power in bar graphs. Confirm the numerical data for the selected order at the same time.

Efficiency and Loss

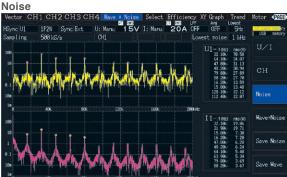


Using active power values and motor power values, confirm efficiency η [%] and loss [W] and total efficiency for each inverter/motor on a single unit at the same time. confirm efficiency $\boldsymbol{\eta}$ [%] and

Selection Display



Select 4/8/16/32 display parameters individually for each screen, and



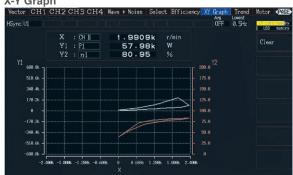
Display FFT results for voltage and current as graphs and numerical values, up to a maximum of 200 kHz. This is perfect for the frequency analysis of inverter noise.

Ver 2.00 // **Trend**



Choose up to eight measurement parameters and display a graph of their variations over time. You can also save a screenshot of the graph.

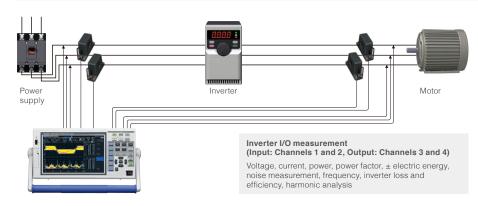
X-Y Graph



Create inverter characteristic evaluations and motor torque maps. Select the desired parameter to display an X-Y plot graph.

Applications

Measure the Power Conversion Efficiency of Inverters

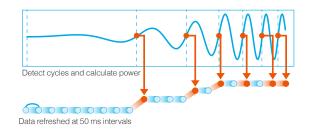


Key features

- Isolated input of voltage and current on each of 4 channels for simultaneous measurement of the primary and secondary power of inverters
- Simultaneous measurement of all important parameters for secondary analysis of inverters, such as RMS value, MEAN value, and fundamental
- Easy wiring with current sensors. Reliable confirmation of wiring with vector diagrams
- 4. Current sensors reduce effects of common mode noise from inverters during power measurement
- 5. Simultaneous measurement of noise components, in addition to the harmonic analysis required for the measurement of inverter control

Highly Accurate and Fast 50 ms **Calculation of Power in Transient State**

Measure power transient states, including motor operations such as starting and accelerating, at 50 ms refresh rates. Automatically measure and keep up with power with fluctuating frequencies, from a minimum of 0.5 Hz.

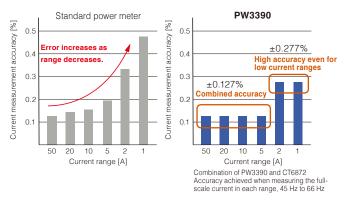


Automatic detection of fundamental wave even if the frequency fluctuates, from low to high frequencies

Achieve high accuracy measurement, including in low current ranges

When used with a high accuracy current sensor*1, the PW3390 delivers exceptional accuracy*2. Achieve high accuracy measurement regardless of range, from high to low currents, even for loads that exhibit significant fluctuation.

Example of combination accuracy with current sensor



- Pass-through type: CT6872, CT6873, CT6875A, CT6876A, CT6877A Clamp type: CT6841A, CT6843A, CT6844A, CT6845A, CT6846A Direct connection type: PW9100A At DC and 50 Hz/60 Hz

Evaluate high-frequency noise / Ver 2.00 // from an inverter

The enhanced noise analysis functionality provided by Version 2.00 of the instrument's firmware lets you perform frequency analysis of noise components from DC to 200 kHz, display and automatically save the top 10 points, and manually save the FFT spectrum. This functionality is an effective tool for evaluating conductive noise from 2 kHz to 150 kHz generated by inverters and switching power supplies.



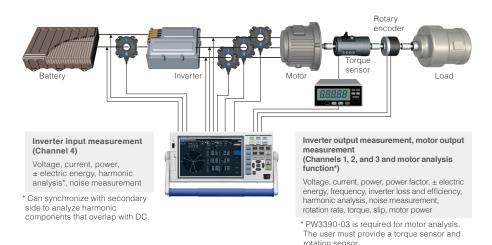
Visually assess temporal fluctuations in efficiency

Ver 2.00 //

The trend display lets you graph user-selected measurement parameters such as efficiency and frequency over periods of time ranging from dozens of seconds to half a month. This capability makes it possible to visually assess fluctuations, including of transient states in which measured values fluctuate abruptly and steady states in which they exhibit minuscule fluctuations. Graphs can be saved as screenshots, and values can be automatically saved.



Analyze and Measure EV/HEV Inverter Motors



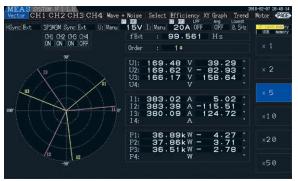
Key features

- Easy wiring and highly accurate measurements with the use of a pass-through type current sensor
- Simultaneous measurement of all important parameters for secondary analysis of inverters, such as RMS value, MEAN value, and fundamental
- 3. 0.5 Hz to 5 kHz harmonic analysis without external clock
- Total measurement of inverter motors with built-in motor analysis function
- Measurement of the voltage, torque, rotation rate, frequency, slip, and motor power required for motor analysis with a single unit
- More precise measurements of electrical angle with incremental type encoders

Electric Angle Measurement of Motors (PW3390-03 only)

Ver 2.00 //

The PW3390-03 features a built-in electric angle measurement function required for vector control via dq coordinate systems in high-efficiency synchronized motors. Make real-time measurements of phase angles for voltage and current fundamental wave components based on encoder pulses. Further, zero-adjustment of the phase angle when induced voltage occurs allows electric angle measurement based on the inductive voltage phase. Version 2.00 of the firmware introduces the ability to display and manually set phase zero-adjustment values, making it possible to measure electrical angle using a user-selected zero-adjustment value. Electric angle can also be used as an Ld and Lq calculation parameter for synchronized motors.



Display motor electric angles on the vector screen

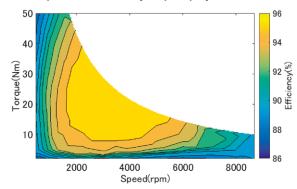
ctor CH1 CH2 CH3 CH4 Wave + Noise Select Effici Sync Ext A: Ana. DC 1 V B: Pulses OFF CH A: **145.26** B: 1.8950k 28.83k 4.79

Motor analysis screen (Torque, rotation rate, motor power, slip) For CH B, enter the Z-phase pulse of the encoder to measure electric angle, and enter the B-phase pulse to measure rotation direction.

Evaluate inverter motor efficiency and loss

Evaluate efficiency and loss for an inverter, motor, and overall system by simultaneously measuring the inverter's input and output power and the motor's output. You can also create an efficiency map or loss map in MATLAB using measurement results recorded by the PW3390 at each operating point.*MATLAB is a registered trademark of Mathworks,

Example of an efficiency map display in MATLAB



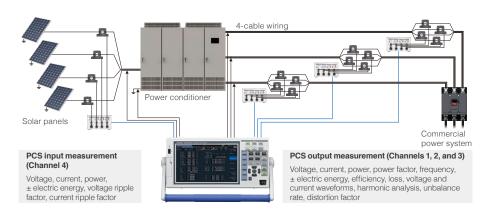
Transfer to Data Logger via Bluetooth® wireless technology

Connect the PW3390 and a data logger (with support of LR8410 Link) via Bluetooth® wireless technology to wirelessly transmit 8 parameters of measurement values from the PW3390 to the data logger. In addition to the voltage, temperature, humidity, and other parameters measured by the multichannel data logger, you can also integrate the measurement values of the PW3390 and observe and record them in real time.



* Connection requires the serial - (Bluetooth® wireless technology) conversion adapter and power supply adapter recommended by Hioki. Please inquire with your Hioki distributor.

Measure the Efficiency of PV Power Conditioners (PCS)



Key features

- 4 built-in channels, standard. Simultaneously measure the I/O characteristics of power conditioners.
- Current sensors can measure even large currents with high accuracy. Reliable confirmation of wiring with vector diagrams.
- Measure the amount of power sold/ purchased from power conditioner output on interconnected systems with a single unit.
- DC mode integration function, which responds quickly to input fluctuations such as with solar power, built in.
- Measure ripple factor, efficiency, loss, and all other parameters that are required for the measurement of power conditioners for solar power with a single unit.

HIOKI's Current Measurement Solutions for Large Currents of 1000 A or More

Introducing a lineup of sensors taking measurements up to 6000 A for 50 Hz/60 Hz, and up to 2000 A for direct current. The CT9557 SENSOR UNIT lets you add the output waveforms from multiple high accuracy sensors. Use multi-cable wiring lines to take highly accurate measurements of up to 8000 A.

			Blue: High accuracy sens	sor Black: Normal sensors	
Recommended current sensor by measurement target		DC powe	System power 50 Hz/60 Hz	Inverter secondary power	
0: 1	1000 A or less		CT6876A or CT6846A		
Single-cable or bundled wiring	2000 A or less	CT6877A or CT7742	CT6877A or CT7642	CT6877A	
wiiiig	6000 A or less	_	CT7044/CT7045/CT7046	_	
2-cable wiring	2000 A or less	CT9557+CT6876A×2 or CT9557+CT6846A×2			
z-cable wiring	4000 A or less	CT9557+CT6877A×2			
2 aabla wiring	3000 A or less	CT9557+CT6876A×3 or CT9557+CT6846A×3			
3-cable wiring	6000 A or less	CT9557+CT6877A×3			
4 aabla wiring	4000 A or less	CT9557-	CT9557+CT6876A×4 or CT9557+CT6846A×4		
4-cable wiring	8000 A or less		CT9557+CT6877A×4		



CT6876A (AC/DC 1000 A)
Pass-through type; Wideband, high accuracy



CT6877A (AC/DC 2000 A)
Pass-through type; Wideband, high accuracy



CT6846A (AC/DC 1000 A) Easy-connect clamp type



CT9557 Add waveforms from multiple current sensors



CT7742 (AC/DC 2000 A) Stable measurement of DC without zero offset



CT7642 (AC/DC 2000 A) Wider frequency characteristics than the CT7742



CT7044/CT7045/CT7046 (AC 6000 A)
Flexible, for easy connections even in narrow

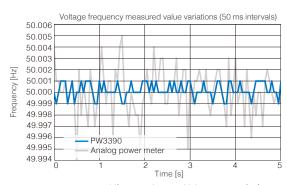
Support for PCS Parameters

Simultaneously display the parameters required for PCS, such as efficiency, loss, DC ripple factor, and 3-phase unbalance rate. Easily check the required measured items for improved test efficiency. By matching the measurement synchronization source for both input and output, you can perform DC power measurements that are synchronized with the output AC as well as stable efficiency measurements.



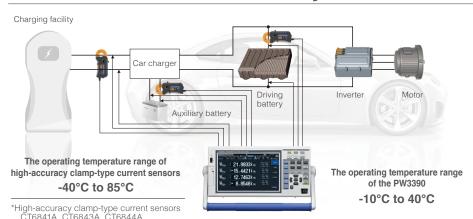
±0.01 Hz^{*} Basic Accuracy for Voltage Frequency Measurements

Perform the frequency measurements that are required for various PCS tests with industry-leading accuracy and stability. Take highly accurate frequency measurements on up to 4 channels simultaneously, while also measuring other parameters at the same time.



* If you require even higher accuracy for frequency, please inquire with your local Hioki distributor.

Test Automobile Fuel Economy



Key features

- Accurately measure recharge and discharge power with excellent basic accuracy and DC accuracy.
- 4 built-in channels, standard. Support for multiple recharge and discharge measurements, including auxiliary batteries.
- Easily achieve highly accurate measurements with clamp sensors, which can be used in a wide range of operating temperatures.
- Perform the -7°C low temperature test (WLTP standards) in the same environment as the automobile.

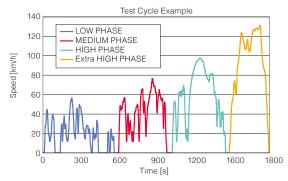


Scan QR Code to Watch Video Illustrating Fuel Economy Evaluation of an Automobile

Evaluate WLTC Mode Performance - A New Fuel Economy Standard

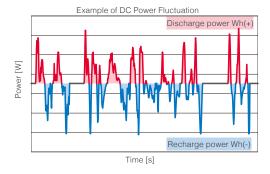
CT6845A, CT6846A

Taking fuel economy measurements that comply with WLTP standards requires the precise measurement of current integration and power integration for the recharging/discharging of each battery in the system. High accuracy clamp current sensors, the excellent DC accuracy of the PW3390, and the ability to integrate current and power at 50 ms intervals are extremely effective in meeting this application. Furthermore, the operating temperature range of the PW3390 has now been extended to reach -10°C, enabling the WLTP measurement in -7°C environments.



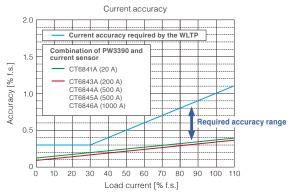
Current and Power Integration Function by Polarity

DC integration measurement integrates the recharging power and discharging power by polarity for every sample at 500 kS/s, and measures positive-direction power magnitude, negative-direction power magnitude, and the sum of positive- and negative-direction power magnitude during the integration period. Accurate measurement of recharging power and discharging power is possible even if there is rapid repetition of battery recharging/discharging.



High-accuracy Current Sensors That Are Ideal for Vehicle Measurement

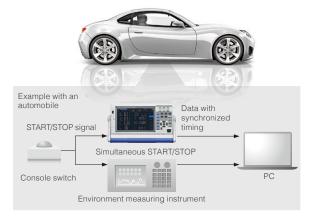
Clamp-type current sensors satisfy the current accuracy requirements imposed by the WLTP, as illustrated in the graph below. Sensors can be easily affixed without cutting cables in circuits under measurement, and they're available with a broad range of ratings (20 A to 1000 A) so that you can choose the right model based on vehicle type and measurement locations.



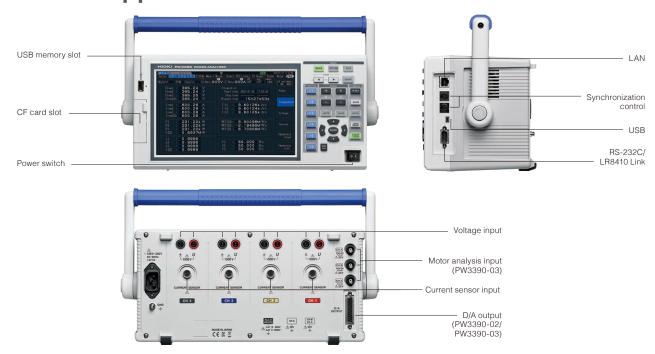
f.s. = Current sensor's rated current (If using a current sensor with a rated current of 500 A, 100% f.s. is 500 A.)

Link to Peripheral Devices via External Control

Use external control terminals to START/STOP integration and capture screen shots. This makes it easy to control operations from console switches and link to the timing of other instruments when measuring the performance of an actual automobile.



External Appearance



Software

Download software, drivers, and the Communications Command Instruction Manual from the Hioki website. https://www.hioki.com

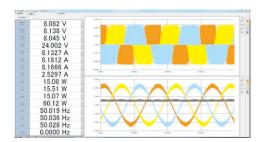
PC Communication Software – PW Communicator

PC Communicator is a free application that connects to the PW3390 via a communications interface (LAN, RS-232C, or GP-IB), making it easy to configure the instrument's

settings and to monitor or save measured values and waveform data from a computer. The software can simultaneously connect to up to 8 Hioki power measuring instruments,

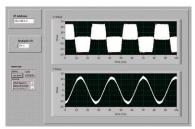
including the PW3390, Power Analyzer PW6001, Power Meter PW3335, PW3336, and PW3337, and it can provide integrated control over multiple models. The software can

also be used to simultaneously save measurement data on the computer and calculate efficiency between instruments.



LabVIEW driver

Use the bundled LabVIEW driver to build a measurement system via a simple programming interface that lets you place icons on a window and connect them with lines. Multiple sample programs for configuring settings and downloading data are available, so you can get started right away.



*LabVIEW is a registered trademark of National Instruments

GENNECT One SF4000

The SF4000 is a free application software that lets you display and save measurement data on a PC in real-time after connecting the PW3390 to the PC via Ethernet.

The application is also compatible with other Hioki measuring instruments such as Memory HiLogger LR8450 and the Wireless Logging Station LR8410, letting you connect up to 30 units at the same time to monitor, graph and display lists of measured values from multiple instruments all at once and in real-time. This is especially effective for performing a total analysis of power, temperature and other factors of equipment.



Remote control using an web browser

Use the PW3390's HTTP server function to connect to a computer via a LAN interface. You can configure settings or check data from a remote location using a virtual control panel that is displayed in the browser window.



Power analyzer lineup

	Model	PW6001	PW8001+U7005	PW8001+U7001	PW3390
			For measurement of SiC	For measurement of	
	Applications	For measurement of high-efficiency IGBT inverters	and GaN inverters and	high-efficiency IGBT inverters and solar inverters	Balance of high accuracy and portability
Appearance			Teactor/Italisionile 1033	inverters and solar inverters	
	Measurement frequency band	DC, 0.1 Hz to 2 MHz	DC, 0.1 Hz to 5 MHz	DC, 0.1 Hz to 1 MHz	DC, 0.5 Hz to 200 kHz
	Basic accuracy for 50/60 Hz power	±(0.02% of reading + 0.03% of range)	±(0.01% of reading + 0.02% of range)	±(0.02% of reading + 0.05% of range)	±(0.04% of reading + 0.05% of range)
	Accuracy for DC power	±(0.02% of reading + 0.05% of range)	±(0.02% of reading + 0.03% of range)	±(0.02% of reading + 0.05% of range)	±(0.05% of reading + 0.07% of range)
	Accuracy for 10 kHz power	±(0.15% of reading + 0.1% of range)	±(0.05% of reading + 0.05% of range)	±(0.2% of reading + 0.05% of range)	±(0.2% of reading + 0.1% of range)
	Accuracy for 50 kHz power	±(0.15% of reading + 0.1% of range)	±(0.15% of reading + 0.05% of range)	±(0.4% of reading + 0.1% of range)	±(0.4% of reading + 0.3% of range)
ers	Number of power measurement channels	1 to 6 channels, a specify when ordering		specify U7001 or order (mixed available)	4 channels
mete	Voltage, current ADC sampling	18-bit, 5 MHz	18-bit, 15 MHz	16-bit, 2.5 MHz	16-bit, 500 kHz
tpara ו	Voltage range	6 V/15 V/30 V/60 V/150 V/ 300 V/600 V/1500 V	6 V/15 V/30 V/60 V/150	V/ 300 V/600 V/1500 V	15 V/30 V/60 V/150 V/ 300 V/600 V/1500V
Measuremen tparameters	Current range	Probe 1: 100 mA to 2000 A (6 ranges, based on sensor) Probe 2: 100 mV, 200 mV, 500 mV, 1 V, 2 V, 5 V	100 mA to 2000 A (6 ranges, based on sensor)	Probe 1: 100 mA to 2000 A (6 ranges, based on sensor) Probe 2: 100 mV, 200 mV, 500 mV, 1 V, 2 V, 5 V	100 mA to 8000 A (6 ranges, based on sensor)
	Common-mode voltage rejection ratio	50/60 Hz: 100 dB or greater 100 kHz: 80 dB typical	50/60 Hz: 120 dB or greater 100 kHz: 110 dB or greater	50/60 Hz: 100 dB or greater 100 kHz: 80 dB typical	50/60 Hz: 80 dB or greater
	Temperature coefficient	0.01%/°C	0.01	%/°C	0.01%/°C
	Voltage input method	Photoisolated input, resistor voltage division	Photoisolated input, resistor voltage division	Isolated input, resistor voltage division	Isolated input, resistor voltage division
	Current input method	Isolated input from current sensor	Isolated input fro	m current sensor	Isolated input from current sensor
	External current sensor input	Yes (ME15W, BNC)	Yes (ME15W)	Yes (ME15W, BNC)	Yes (ME15W)
	Power supplied to external current sensor	Yes	Y	es	Yes
	Data update rate	10 ms, 50 ms, 200 ms	10 ms, 50 i	ms, 200 ms	50 ms
/oltage input	Maximum input voltage	1000 V,±2000 V peak (10 ms)	1000 V,±2000 V peak	1000 V AC, 1500 V DC, ±2000 V peak	1500 V, ±2000 V peak
	Maximum rated line-to-ground voltage	600 V CAT III 1000 V CAT II	600 V CAT III 1000 V CAT II	600 V AC/1000 V DC CAT III 1000 V AC/1500 V DC CAT II	600 V CAT III 1000 V CAT II
alysis	Number of motor analysis channels	Maximum 2 motors*1	Maximum	4 motors*1	Maximum 1 motors*1
Ang	Motor analysis input format	Analog DC, frequency, pulse	-	equency, pulse	Analog DC, frequency, pulse
	Current sensor phase shift calculation	Yes		auto)	Yes
	Harmonics measurement	Yes (6, for each channel)		ach channel)	Yes
	Maximum harmonics analysis order	100th		Oth Other A Mile	100th
_	Harmonics synchronization frequency range	0.1 Hz to 300 kHz	0.1 Hz to 1.5 MHz	0.1 Hz to 1 MHz s*2	0.5 Hz to 5 kHz
Function	IEC harmonics measurement IEC flicker measurement	Yes		S*2	-
교	FFT spectrum analysis	Yes (DC to 2 MHz)	Yes*2 (DC ~ 4 MHz)	Yes*2 (DC ~ 1 MHz)	Yes (DC to 200 kHz)
	User-defined calculations	Yes	` ′	s*2	-
	Delta conversion	Yes (Δ-Y, Y-Δ)	Yes (Δ-Y, Y-Δ)		Yes (Δ-Y)
	D/A output	Yes*1 20 ch (waveform output, analog output)	Yes*1 20 ch (waveform output, analog output)		Yes*1 16 ch (waveform output, analog output)
Display	Display	9" WVGA TFT color LCD	10.1" WVGA	ΓFT color LCD	9" WVGA TFT color LCD
Disp	Touch screen	Yes	Yes		-
	External storage media USB 2.0 USB 3.0		3 3.0	USB 2.0, CF card Yes	
	LAN (100BASE-TX, 1000BASE-T)	Yes	Yes		(10BASE-T and 100BASE-TX only)
ace	GP-IB RS-232C	Yes Yes (maximum 230,400 bps)	Yes		Yes (maximum 38,400 bps)
Interface	External control	Yes (maximum 230,400 bps)	Yes (maximum 115,200 bps) Yes		Yes (maximum 38,400 bps)
=	Synchronization of multiple instruments	res -		l instruments)	Yes (up to 8 instruments)
	Optical link	Yes	` '	* instruments) 	-
	CAN or CAN FD	-		*1*2	-
Din	nensions, weight (WxHxD)	430 mm (16.93 in.) × 177 mm (6.97 in.) × 450 mm (17.72 in.) 14 kg (493.84 oz.)	430 mm (16.93 in.) × 221 mm	(8.70 in.) × 361 mm (14.21 in.) 33.84 oz.)	340 mm (13.39 in.) × 170 mm (6.69 in.) × 156 mm (6.14 in.) 4.6 kg (162.26 oz.)
			ı	* ¹ · Sol	d separately *2: Release in 2022

Specifications

Basic Specifications

Accuracy guaranteed for 6 months (and 1.25 times specified accuracy for one year)

-1. Power Measure					
Measurement line type	Single-phase 2- (3P3W2M, 3P3V		ingle-phase 3-wir 4-wire (3P4W)	e (1P3W), 3-phas	se 3-wire
		CH1	CH2	CH3	CH4
	Pattern 1	1P2W	1P2W	1P2W	1P2W
	Pattern 2		P3W	1P2W	1P2W
	Pattern 3		3W2M	1P2W	1P2W
	Pattern 4 Pattern 5		P3W 3W2M	1P3	
	Pattern 6		3W2M	3P3V	
	Pattern 7		3P3W3M		1P2W
	Pattern 8		3P4W		1P2W
Number of input channels	Voltage: 4 chanr	nels U1 to U4, (Current: 4 channe	ls I1 to I4	
Measurement input	Voltage: Plug-in				
terminal type Input methods	Voltage: Isolated		nectors (ME15W) ve dividers		
·	Current: Insulate	ed current sens	ors (voltage outpu	ut)	
Voltage range	15 V/30 V/60 V/1 (Selectable for		0 V/1500 V d wiring system. A	UTO range avail	able.)
Current range	2 A/4 A/8 A/20 A	A		(with the	9272-05, 20 A
(): Sensor used	0.4 A/0.8 A/2 A/4 4 A/8 A/20 A/40			(with the (200 A se	CT6841A)
(). Serisor used	40 A/80 A/200 A		2 kA	(2000 A s	sensor)
	0.1 A/0.2 A/0.5 A 1 A/2 A/5 A/10 A			(5 A sens	
	10 A/20 A/50 A/	100 A/200 A/50		(500 A se	ensor)
	20 A/40 A/100 A 400 A/800 A/2 k		1 kA	(1000 A s	ensor) and CT7742)
	400 A/800 A/2 k			(CT7044,	CT7045,
	400 A/800 A/2 k			and CT70 (100 uV/A	
	40 A/80 A/200 A 4 A/8 A/20 A/40	A/400 A/800 A/		(1 mV/A s	ensor)
	0.4 A/0.8 A/2 A/-	4 A/8 A/20 A		(10 mV/A (100 mV//	A sensor)
	-		wiring system. Al		
Power range	1.5000 W to 90.0 range, current ra		nined automaticall surement line.	y by the combina	ation of voltage
Effective measuring			110% of the range	9	
range					
Total display area			zero-suppression	range setting to	120%
Zero-suppression ranges	Selectable OFF, When OFF, non-		i. ay be displayed ev	en with no meas	urement inpu
Zero adjustment			pensation of interr		
Waveform peak			ensation of input of and current range		10% f.s. ±4 m\
measurement range	WILIIII ±300% 0	reacti voltage	and current range		
Waveform peak	Within ±2% f.s.	of voltage and	current display ac	curacy	
measurement accuracy Crest factor	300 (relative to minimum effective voltage/current input) (for 1500 V range: 133)				
01001140101	3 (relative to voltage/current range rating) (for 1500 V range: 1.33)				
Input resistance	Voltage input sec		: 2 MΩ ±40 kΩ (dit : 1 MΩ ±50 kΩ	ferential input and	l insulated inpu
(50 Hz/60 Hz) Maximum input voltage	Current sensor in Voltage input se	-	: 1500 V, ±2000 V	/neak	
	Current sensor i	nput section	: 5 V, ±10 Vpeak		
Maximum rated voltage to earth	Voltage input ter		50 Hz/60 Hz) 0 V (anticipated tr	ansient overvolta	age 6000 V)
	Measurement ca	ategories II 100	00 V (anticipated to	ransient overvolt	age 6000 V)
Measurement method	Simultaneous di zero-crossing ca		of voltage and cur	rent, simultaneo	us
Sampling	500 kHz/16 bit	ziodiation metri	00		
Measurement	DC, 0.5 Hz to 20	00 kHz			
frequency range					
Synchronization frequency range	0.5 Hz to 5 kHz Selectable lower	limit measuren	nent frequency (0.5	Hz/1 Hz/2 Hz/5 H	Hz/10 Hz/20 Hz
Synchronization source			motor evaluation in		
,	pulse input),				
	DC (50 ms or 100 ms fixed) Selectable for each measurement channel (U/I for each channel measured using				
	the same synchronization source) The zero-crossing filter automatically matches the digital LPF when U or I is selected.				
	The filter levels (strong or mild) Operation and accuracy are undetermined when the zero-crossing filter is disabled (off)				
			termined when the termined when U o		
	input is 30% f.s.				
Data update interval	50 ms				
LPF			electable for each		
	500 Hz: Accuracy defined at 60 Hz or below (Add ±0.1% f.s.) 5 kHz: Accuracy defined at 500 Hz or below				
			0 kHz or below (A	dd 1% rdg. at or	above 10 kHz
	Off, mild or strong				
				method	
	Voltage/current				
Polarity discrimination	Zero-crossing fil	Iter provided by	/ digital LPF	cation DMS equiv	alent voltage
Polarity discrimination Basic measurement	Zero-crossing fill Frequency, RMS AC component, v	voltage, voltage voltage simple a	/ digital LPF e mean value rectifi verage, voltage fun	damental wave co	omponent,
Polarity discrimination Basic measurement	Zero-crossing fil Frequency, RMS AC component, v voltage waveform	voltage, voltage voltage simple a n peak +, voltage	v digital LPF e mean value rectifi verage, voltage fun e waveform peak -,	damental wave co voltage total harm	omponent, ionic distortion,
Polarity discrimination Basic measurement	Zero-crossing fill Frequency, RMS AC component, v voltage waveform voltage ripple fac rectification RMS	voltage, voltage voltage simple and peak +, voltage tor, voltage unbased	e mean value rectifi verage, voltage fun e waveform peak -, alance factor, RMS rent AC componen	damental wave co voltage total harm current, current n t, current simple a	omponent, ionic distortion, nean value verage, current
Polarity discrimination Basic measurement	Zero-crossing fil Frequency, RMS AC component, v voltage waveform voltage ripple fac rectification RMS fundamental wav	voltage, voltage voltage simple and peak +, voltage tor, voltage unbased equivalent, curve component, c	digital LPF e mean value rectification verage, voltage funder waveform peak -, alance factor, RMS	damental wave co voltage total harm current, current n t, current simple a eak +, current wave	omponent, nonic distortion, nean value verage, current eform peak
Polarity discrimination Basic measurement	Zero-crossing fill Frequency, RMS AC component, v voltage waveform voltage ripple fac rectification RMS fundamental wav -, current total har active power, app	Iter provided by voltage, voltage, voltage simple as a peak +, voltage tor, voltage unb. equivalent, cur e component, crrmonic distortion parent power, re-	r digital LPF mean value rectifi verage, voltage fun e waveform peak -, alance factor, RMS rent AC componen urrent waveform pe n, current ripple fac active power, powe	damental wave co voltage total harm current, current nt, t, current simple a eak +, current wave tor, current unbalar r factor, voltage pl	omponent, nonic distortion, nean value verage, current eform peak ance factor, hase angle
Polarity discrimination Basic measurement	Zero-crossing fill Frequency, RMS AC component, v voltage waveform voltage ripple fac rectification RMS fundamental wav -, current total hau active power, app current phase an negative-direction	voltage, voltage, voltage simple at n peak +, voltage unbut or, voltage unbut e equivalent, current power, regle, power phas n current magni	r digital LPF e mean value rectifi everage, voltage fun e waveform peak -, alance factor, RMS rent AC componen urrent waveform pe n, current ripple fac active power, powe e angle, positive-di tude, sum of positiv	damental wave or voltage total harm current, current in t, current simple a veak +, current wave tor, current unbala in factor, voltage placetion current made are and negative-of and negative-of voltage placetion current made and negative-of and negative-of voltage placetion and negative-of and and negative-of and negative-of an	omponent, sonic distortion sean value verage, curren eform peak nace factor, nase angle agnitude, lirection curren
Polarity discrimination Basic measurement	Zero-crossing fill Frequency, RMS AC component, voltage waveform voltage ripple fac rectification RMS fundamental wav-, current total har active power, approximate programment phase an negative-direction magnitude, positi	Iter provided by voltage, voltage, voltage, voltage, voltage simple a n peak +, voltage tot, voltage unb. e e component, c rmonic distortion parent power, re ggle, power phas n current magnifive-direction pover.	r digital LPF e mean value rectificereae, voltage fun e waveform peak -, alance factor, RMS rent AC componen urrent waveform pe active power, powe e angle, positive-di tude, sum of positiv wer magnitude, neg	damental wave or voltage total harm current, current nt, current simple a eak +, current wavetor, current unbalar factor, voltage pl rection current mare and negative-dijativ	omponent, nonic distortion nean value verage, curren eform peak ance factor, nase angle agnitude, lirection curren wer magnitude
Polarity discrimination Basic measurement	Zero-crossing fil Frequency, RMS AC component, voltage waveform voltage waveform voltage ripple fac rectification RMS fundamental wav , current total har active power, apc current phase an negative-direction magnitude, positi sum of positive-a	Iter provided by voltage, voltage, voltage, voltage, voltage simple a n peak +, voltage tot, voltage unb. e e component, c rmonic distortion parent power, re ggle, power phas n current magnifive-direction pover.	r digital LPF e mean value rectifi everage, voltage fun e waveform peak -, alance factor, RMS rent AC componen urrent waveform pe n, current ripple fac active power, powe e angle, positive-di tude, sum of positiv	damental wave or voltage total harm current, current nt, current simple a eak +, current wavetor, current unbalar factor, voltage pl rection current mare and negative-dijativ	omponent, nonic distortion nean value verage, curren eform peak nace factor, nase angle agnitude, lirection curren wer magnitude
Zero-crossing filter Polarity discrimination Basic measurement parameters	Zero-crossing fil Frequency, RMS AC component, voltage waveform voltage vaveform voltage ripple fac rectification RMS fundamental wav -, current total hai active power, opp current phase an negative-direction magnitude, positi sum of positive- a (PW3390-03)	Iter provided by voltage, voltage, voltage simple a n peak +, voltage tor, voltage unbi- equivalent, cur e component, c rmonic distortionarent power, regle, power phas n current magnifive-direction povand negative-direction povand negative-directions.	v digital LPF mean value rectifi everage, voltage fun waveform peak -, alance factor, RMS rent AC componen urrent waveform pe, n, current ripple fac active power, powe e angle, positive-di tude, sum of positiv wer magnitude, neg ection power magn	damental wave or voltage total harm current, current nt, current simple a eak +, current wavetor, current unbalar factor, voltage pl rection current mare and negative-dijativ	omponent, nonic distortion nean value verage, curren eform peak ance factor, nase angle agnitude, lirection curren wer magnitude
Polarity discrimination Basic measurement parameters	Zero-crossing fil Frequency, RMS AC component, voltage waveform voltage waveform voltage ripple fac rectification filter fundamental wav , current total hai active power, current phase an negative-direction magnitude, positi sum of positive- (PW3390-03) Motor torque, rp	Iter provided by voltage, voltage, voltage simple a npeak +, voltage tor, voltage unb. e quivalent, cur e component, crmonic distortion arent power, regle, power phas no current magni ve-direction power and negative-direction power, m, motor power, m, m, motor power.	v digital LPF mean value rectifi verage, voltage fun verage, voltage verage, voltage verage, voltage verage, voltage verage v	damental wave co voltage total harm current, current nt, t, current simple a take, current wave tor, current unbale r factor, voltage pi rection current me- e- and negative pative-direction po itude, efficiency, li	omponent, ionic distortion ionic distortion ionic distortion ionic mean value verage, curren eform peak ince factor, nase angle agnitude, lirection curren wer magnitude oss
Polarity discrimination Basic measurement	Zero-crossing fil Frequency, RMS AC component, v voltage waveform voltage ripple fac rectification flore from the first fundamental wav -, current total han active power, apc current phase an engalitve-direction magnitude, positi sum of positive- e (PW330-03) Motor torque, rp Select which vol reactive power, apcative the first fundamental from the first fundamental fundamenta	Iter provided by voltage, voltage, voltage simple a n peak +, voltage tor, voltage unb. equivalent, cur e component, c rmonic distortio parent power, re gle, power phas n current magni ve-direction power and negative-dir m, motor powe tage and curre and power fact	r digital LPF mean value rectifi verage, voltage fun waveform peak -, alance factor, RMS alance factor, RMS rent AC componen urrent waveform pe n, current ripple fac active power, powe e angle, positive-di tude, sum of positive-di tude sum of tude of the component r, slip nt values to use fo or	damental wave covoltage total harm current, current in , current simple a sk4 +, current pask +, current current unbage la reaction current unbage la rection current ma e- and negative-direction po- titude, efficiency, la por calculating app	omponent, tonic distortion to mean value verage, curren eform peak tone factor, nase angle agnitude, lirection curren wer magnitude oss
Polarity discrimination Basic measurement parameters Voltage/current	Zero-crossing fil Frequency, RMS AC component, v voltage waveform voltage ripple fac rectification flore from the first fundamental wav -, current total han active power, apc current phase an engalitve-direction magnitude, positi sum of positive- e (PW330-03) Motor torque, rp Select which vol reactive power, apcative the first fundamental from the first fundamental fundamenta	Iter provided by voltage, voltage, voltage simple a roltage simple a roltage simple a equivalent, cure component, crimonic distortion parent power, regle, power phas in current magnitive-direction power and negative-direction power, m, motor power tage and current and power fact tage and current and curre	r digital LPF mean value rectifi werage, voltage fun waveform peak -, alance factor, RMS alance factor, RMS catche pose urrent AC componen urrent waveform pe n, current ripple fac active power, powe e angle, positive-di tude, sum of positive-di tude of tude of tude of tude tude of tude of tude of tude of tude tude of tude of tude of tude of tude tude of tude of tude of tude of tude of tude tude of tud	damental wave covoltage total harm current, current in t, current simple a sk4 +, current public to total current unbage pl rection current made e- and negative-direction po- titude, efficiency, li	omponent, ionic distortion ionic distortion ionic distortion ionic mean value verage, curren eform peak ince factor, nase angle agnitude, lirection curren wer magnitude oss

Accuracy		Voltage (U)	Current (I)	
	DC	±0.05% rdg. ±0.07% f.s.	±0.05% rdg. ±0.07% f.s.	
	0.5 Hz ≤ f < 30 Hz	±0.05% rdg. ±0.1% f.s.	±0.05% rdg. ±0.1% f.s.	
	30 Hz ≤ f < 45 Hz	±0.05% rdg. ±0.1% f.s.	±0.05% rdg. ±0.1% f.s.	
	45 Hz ≤ f ≤ 66 Hz	±0.04% rdg. ±0.05% f.s.	±0.04% rdg. ±0.05% f.s.	
	66 Hz < f ≤ 1 kHz	±0.1% rdg. ±0.1% f.s.	±0.1% rdg. ±0.1% f.s.	
	1 kHz < f ≤ 10 kHz		±0.1% rdg. ±0.1% f.s.	
		±0.2% rdg. ±0.1% f.s.	-	
	10 kHz < f ≤ 50 kHz	±0.3% rdg. ±0.2% f.s.	±0.3% rdg. ±0.2% f.s.	
	50 kHz < f ≤ 100 kHz	±1.0% rdg. ±0.3% f.s.	±1.0% rdg. ±0.3% f.s.	
	100 kHz < f ≤ 200 kHz	±20% f.s.	±20% f.s.	
		Active power (P)	Phase difference	
	DC	±0.05% rdg. ±0.07% f.s.	-	
	0.5 Hz ≤ f < 30 Hz	±0.05% rdg. ±0.1% f.s.	±0.08°	
	30 Hz ≤ f < 45 Hz	±0.05% rdg. ±0.1% f.s.	±0.08°	
	45 Hz ≤ f ≤ 66 Hz	±0.04% rdg. ±0.05% f.s.	±0.08°	
	66 Hz < f ≤ 1 kHz	±0.1% rdg. ±0.1% f.s.	±0.08°	
	1 kHz < f ≤ 10 kHz	±0.2% rdg. ±0.1% f.s.	±(0.06*f+0.02)°	
	10 kHz < f ≤ 50 kHz	±0.4% rdg. ±0.3% f.s.	±0.62°	
	50 kHz < f ≤ 100 kHz	±1.5% rdg. ±0.5% f.s.	±(0.005*f+0.4)°	
	100 kHz < f ≤ 200 kHz		±(0.022*f-1.3)°	
	Values of f in above tables	±20% f.s.	±(0.022 I=1.3)	
Conditions of	power factor of zero and th Accuracy figures for voltage range of 0.5 Hz to 10 Hz an Accuracy figures for voltage frequency range of 10 hz to Accuracy figures for voltage frequency range of 30 kHz Accuracy figures for voltage the frequency range of 100 k Accuracy figures for voltage provided as reference value Accuracy figures for phase to 66 Hz are provided as re For voltages in excess of 66 500 Hz < f ≤ 5 kHz:±0.5° 5 kHz ≤ 200 kHz:±10.5° 20 kHz < f ≤ 200 kHz:±10.5° Add ±20 μV to the DC cur Add current sensor accura power, and phase differen are defined for current me sensor specifications). Apply LPF accuracy defini	e, current, and active power e provided as reference value e and active power values in 16 Hz are provided as refere and active power values in to 100 kHz are provided as rand active power values in ex Hz to 200 kHz are provided as rand active power values in ex hz to 200 kHz are provided with the composition of the	values in the frequency es. excess of 220 V in the ence values. excess of 750 V in the efference values. excess of (22,000 f [kHz]) V in sreference values. excess of 1000 V are efference values. excess of 1000 V are efference accuracy phase difference accuracy phase difference accuracy (at 2 V f.s.) es for current, active bination accuracy figures ges 16 to 18 of the current figures when using the LPF	
guaranteed accuracy Temperature coefficient	80% R.H. or less Warm-up time: 30 min. or Input: Within the specified with the sync source zero ground voltage adjustment and with the synchronization ±0.01% rdg./°C (for DC, ac	more I ranges when the fundame e, for sine wave input, powe t, within effective measuren in the range in which the fu source conditions	ntal wave is synchronized or factor of one, or DC inpu nent range after zero- indamental wave satisfies	
voltage	measurement jacks and ch		y .	
Magnetic field interference		m magnetic field, DC and 50		
Power factor influence	Other than $\phi=\pm90^\circ$: $\pm(1-\cos{(\phi+Phase\ difference\ accuracy)/cos(\phi)})\times100^\circ\ rdg.$ When $\phi=\pm90^\circ$: $\pm\cos{(\phi+Phase\ difference\ accuracy)}\times100^\circ\ f.s.$			
Susceptibility to conducted electromagnetic field	@3 V, current and active power not more than ±6% f.s., where f.s. current is the rated primary-side current of the current sensor f.s. active power equals the voltage range × the rated primary-side current of the current sensor			
Susceptibility to radiated electromagnetic field	@10 V/m, current and active power not more than ±6% f.s., where f.s. current is the rated primary-side current of the current sensor			
2. Frequency Mea	asurement Specifications			
Measurement channels	Four (f1 to f4)			
Measurement source	Select U/I for each measu	rement channel		
Measurement method		-crossing sample value cor	rection	
Measuring range		Hz to 5 kHz (with "0.0000 Hz" or		
Lower limit	0.5 Hz/1 Hz/2 Hz/5 Hz/10			
measurement frequency Data update interval	50 ms (measurement from	uency-dependent at 45 Hz	and helow)	
Accuracy	+0.01 Hz (during voltage fre			

2. I requestly ineasurement opecifications			
Measurement channels	Four (f1 to f4)		
Measurement source	Select U/I for each measurement channel		
Measurement method	Reciprocal method + zero-crossing sample value correction		
Measuring range	Synchronous range from 0.5 Hz to 5 kHz (with "0.0000 Hz" or " Hz" unmeasurable time)		
Lower limit	0.5 Hz/1 Hz/2 Hz/5 Hz/10 Hz/20 Hz		
measurement frequency			
Data update interval	50 ms (measurement-frequency-dependent at 45 Hz and below)		
Accuracy	± 0.01 Hz (during voltage frequency measurement within the range of 45 Hz to 66 Hz) $\pm 0.05\%$ rdg., ± 1 dgt. (under other conditions) With sine wave of at least 30% of the measurement source's measurement range		
Numerical display format	0.5000 Hz to 9.9999 Hz, 9.900 Hz to 99.999 Hz, 99.00 Hz to 999.99 Hz, 0.9900 kHz to 5.0000 kHz		

-3. Integration Measurement Specifications

Measurement mode	Selectable between RMS or DC for each wiring mode
Measurement items	Current integration (Ih+, Ih-, and Ih), active power integration (WP+, WP-, and WP) Ih+ and Ih- only for DC mode measurements, and Ih only for RMS mode measurements
Measurement method	Digital calculation from each current and active power phase (when averaging, calculates with previous average value) In DC mode: calculates current value at every sample, and integrates instantaneous power independent of polarity In RMS mode: Integrates current effective values between measurement intervals, and polarity-independent active power value
Measurement interval	50 ms data update interval
Measuring range	Integration value: 0 Ah/Wh to ±9999.99 TAh/TWh Integration time: No greater than 9999h59m
Integration time accuracy	±50 ppm ±1 dgt. (-10°C to 40°C (14°F to 104°F))
Integration accuracy	± (current and active power accuracy) ± integration time accuracy
Backup function	Integration automatically resumes after power outages.

-4 Harmonic Measurement Specifications

Number of measurement channels	4 channels Harmonic measurements not available for multiple systems with different frequencies.			
Measurement items	Harmonic rms voltage, harmonic voltage percentage, harmonic voltage phase angle, harmonic ms current, harmonic current percentage, harmonic current phase angle, harmonic active power, harmonic power percentage, harmonic voltage-current phase difference, total harmonic voltage distortion, total harmonic current distortion, voltage unbalance factor, current unbalance factor			
Measurement method	Zero-crossing synchronous calculation (all channels in same window), with gap Fixed 500 kS/s sampling, after digital anti-aliasing filter Equal thinning between zero crossings (with interpolation calculation)			
Harmonic sync source	U1 to U4, I1 to I4, External (with motor analysis and CH B set for pulse input), DC selectable (50 ms or 100 ms)			
FFT calculation word length	32 bits			
Anti-aliasing filter	Digital filter (automatically set based on synchronization frequency)			
Windows	Rectangular			
Synchronization frequency range	As specified for power measurements			
Data update interval	50 ms (measurement-frequency-dependent at 45 Hz and below)			
Phase zero adjustment	Provided by key operation or external control command (only with external sync source) Automatic or manual configuration of phase zero-adjustment values Phase zero-adjustment setting range: 0.00° to ±180.00° (in 0.01° increments)			
THD calculation	THD-F/THD-R			
Highest order analysis and window waveforms	Synchronization frequency range	Window waveforms	Analysis order	
	0.5 Hz ≤ f < 40 Hz	1	100th	1
	40 Hz ≤ f < 80 Hz	1	100th	1
	80 Hz ≤ f < 160 Hz	2	80th	1
	160 Hz ≤ f < 320 Hz	4	40th	1
	320 Hz ≤ f < 640 Hz	8	20th	1
	640 Hz ≤ f < 1.2 kHz	16	10th	
	1.2 kHz ≤ f < 2.5 kHz	32	5th	
	2.5 kHz ≤ f < 5.0 kHz	64	3th]
Accuracy	Frequency	Voltage(U), Ci	urrent(I), Active Por	wer(P)
	0.5 Hz < f < 30 Hz	±0.4% rda, ±0	.2% f.s.	

Not specified for sync frequencies of 4.3 kHz and higher Add the LPF accuracy to the above when using LPF. -5. Noise Measurement Specifications

30 Hz ≤ f ≤ 400 Hz

400 Hz < f ≤ 1 kHz

10 kHz < f ≤ 13 kHz

1 kHz < f ≤ 5 kHz 5 kHz < f ≤ 10 kHz

Calculation channels	1 (Select one from CH1 to CH4)
Calculation items	Voltage noise/Current noise
Calculation type	RMS spectrum
Calculation method	Fixed 500 kS/s sampling, thinning after digital anti-aliasing filter
FFT calculation word length	32 bits
FFT data points	1000/5000/10,000/50,000 (according to displayed waveform recording length)
Anti-aliasing filter	Automatic digital filter (varies with maximum analysis frequency)
Windows	Rectangular/Hanning/flat-top
Data update interval	Determined by FFT points within approx. 400 ms, 1 s, 2 s, or 15 s, with gap
Highest analysis frequency	200 kHz/50 kHz/20 kHz/10 kHz/5 kHz/2 kHz
Frequency resolution	0.2 Hz to 500 Hz (Determined by FFT points and maximum analysis frequency)
Noise amplitude measurement	Calculates the ten highest level and frequency voltage and current FFT peak values (local maxima).
Lower limit noise frequency	0 kHz to 10 kHz

±0.3% rdg. ±0.1% f.s.

±0.4% rdg. ±0.2% f.s. ±1.0% rdg. ±0.5% f.s.

±2.0% rdg. ±1.0% f.s.

±5.0% rdg. ±1.0% f.s.

-6. Motor Analysis Specifications (Model PW3390-03)

Number of input channels	3 channels CH A: Analog DC input/Frequency input (selectable) CH B: Analog DC input/Pulse input (selectable) CH Z: Pulse input
Measurement input terminal type	Insulated BNC jacks
Input impedance (DC)	1 MΩ ±100 kΩ
Input methods	Isolated and differential inputs (not isolated between channels B and Z)
Measurement items	Voltage, torque, rotation rate, frequency, slip, and motor power
Synchronization source	U1 to U4, I1 to I4, Ext (with CH B set for pulse input), DC (50 ms/100 ms) Common to channels A and B
Measurement frequency source	f1 to f4 (for slip calculations)
Maximum input voltage	±20 V (during analog, frequency, and pulse input)
Maximum rated voltage to earth	50 V (50 Hz/60 Hz)

(1). Analog DC Input (CH A/CH B)

M	±1 V, ±5 V, ±10 V (when inputting analog DC)
Measurement range	±1 V, ±5 V, ±10 V (when inputting analog DC)
Valid input range	1% to 110% f.s.
Sampling	10 kHz/16 bits
Response time	1 ms (measuring zero to full scale, with LPF off)
Measurement method	Simultaneous digital sampling and zero-crossing synchronous calculation system (cumulative average of intervals between zero crossings)
Measurement accuracy	±0.08% rdg. ±0.1% f.s.
Temperature coefficient	±0.03% f.s./°C
Effect of common mode voltage	Not more than ±0.01% f.s. (with 50 V [DC or 50 Hz/60 Hz] between measurement jacks and PW3390 chassis)

Effect of external magnetic field	Not more than ±0.1% f.s. (at 400 A/m DC and 50 Hz/60 Hz magnetic fields)
LPF	OFF/ON (OFF: 4 kHz, ON: 1 kHz)
Total display area	Zero-suppression range setting ±120%
Zero adjustment	Zero-corrected input offset of voltage ±10% f.s. or less
Scaling	0.01 ~ 9999.99
Unit	CH A: V, N _* m, mN _* m, kN _* m, CH B: V, Hz, r/min

(2). Frequency Input (CH A only)

Valid amplitude range	±5 V peak (5 V symmetrical, equivalent to RS-422 complementary signal)
Max. measurement frequency	100 kHz
Measurement range	1 kHz to 100 kHz
Data output interval	According to synchronization source
Measurement accuracy	±0.05% rdg., ±3 dgt.
Total display area	1.000 kHz to 99.999 kHz
Frequency range	Select fc and fd for frequency range fc \pm fd [Hz] (frequency measurement only) 1 kHz to 98 kHz in 1 kHz units, where fc $+$ fd $<$ 100 kHz and fc $-$ fd $>$ 1 kHz
Rated torque	1 ~ 999
Unit	Hz, N• m, mN• m, kN• m

(3). Pulse Input (CH B only)

Detection level	Low: 0.5 V or less; High: 2.0 V or more
Measurement range	1 Hz to 200 kHz (at 50% duty)
Division setting range	1 ~ 60000
Measurement frequency range	0.5 Hz to 5.0 kHz (limited to measured pulse frequency divided by selected no. of divisions)
Minimum detectable pulse width	2.5 µs or more
Measurement accuracy	±0.05% rdg., ±3 dgt.
Motor poles	2 ~ 98
Max. measurement frequency	100 Hz, 500 Hz, 1 kHz, 5 kHz
Pulse count	Integer multiple of half the number of motor poles, from 1 to 60,000
Unit	Hz, r/min

(4). Pulse Input (CH Z only)

Detection level	Low: 0.5 V or less; High: 2.0 V or more
Measurement range	0.1 Hz to 200 kHz (at 50% duty)
Minimum detectable pulse width	2.5 µs or more
	OFF/Z Phase/B Phase (clear counts of CHB in rising edge during Z Phase, detect polar code for number of rotations during B Phase)

-7. D/A Output Option Specifications (Models PW3390-02 and PW3390-03)

	,
Number of output channels	16 channels
Output contents	CH1 to CH8: Selectable analog/waveform outputs CH9 to CH16: Analog output
Output items	Analog output: Select a basic measurement item for each output channel. Waveform output: Output voltage or current measured waveforms.
Output connector	One 25-pin female D-sub
D/A conversion resolution	16 bits (polarity + 15 bits)
Output accuracy	Analog output: Measurement accuracy ±0.2% f.s. (DC level) Waveform output: Measurement accuracy ±0.5% f.s. (at ±2 V f.s.), ±1.0% f.s. (at ±1 V f.s.) (rms level within synchronous frequency range)
Output update interval	Analog output: 50 ms (according to input data update interval of selected parameter) Waveform output: 500 kHz
Output voltage	Analog output: ±5 V DC nom. (approx. ±12 V DC max.) Waveform output: ±2 V/±1 V switchable, crest factor of 2.5 or greater Setting applies to all channels.
Output impedance	100 Ω ±5 Ω
Temperature coefficient	±0.05% f.s./°C

-8. Display Specifications

Display type	9-inch TFT color LCD (800×480 dots)
Display refresh interval	Measurement values: 200 ms (independent of internal data update interval)
	Waveforms, FFT; screen-dependent

-9. External Interface Specifications

(1). USB Interface (Functions)

	·
Connector	Mini-B receptacle ×1
Compliance standard	USB2.0 (Full Speed/High Speed)
Class	Individual (USB488h)
Connection destination	Computer (Windows10/Windows8/Windows7, 32bit/64bit)
Function	Data transfer and command control

(2). USB Memory Interface

Connector	OSB type A connector x1
Compliance standard	USB2.0
USB power supply	500 mA maximum
USB storage device support	USB Mass Storage Class
Function	Save and load settings files, Save waveform data Save displayed measurement values (CSV format) Copy measurement values and recorded data (from CF card) Save waveform data Save FFT spectrum for noise measurement Save/load screenshots

(3). LAN Interface

Connector	RJ-45 connector × 1
Compliance standard	IEEE 802.3 compliant
Transmission method	10BASE-T/100BASE-TX Auto detected
Protocol	TCP/IP
Function	HTTP server (remote operation), Dedicated port (data transfer and command control)

(4). CF Card Interface

Slot	One Type 1
Compatible card	CompactFlash memory card (32 MB or higher)
Supported memory capacity	Up to 2 GB
Data format	MS-DOS format (FAT16/FAT32)
Recordable content	Save and load settings files, Save waveform data Save displayed measurement values and auto-recorded data (CSV format) Copy measurements/recorded data (from USB storage) Save waveform data Save FFT spectrum for noise waveforms Save/load screenshots

(5). RS-232C Interface

Method	RS-232C, [EIA RS-232D], [CCITT V.24], [JIS X5101] compliant Full duplex, start-stop synchronization, 8-bit data, no parity, one stop bit Hardware flow control, CR+LF delimiter
Connector	D-sub9 pin connector ×1
Communication speeds	9600 bps, 19,200 bps, 38,400 bps
Function	Command control, Bluetooth® logger connectivity (simultaneous use not supported)
(6) Synchronization Control Interface	

	Signal contents	One-second clock, integration START/STOP, DATA RESET, EVENT
	Connector types	IN: One 9-pin female mini-DIN jack, OUT: One 8-pin female mini-DIN jack
	Signal	5 V CMOS
	Max. input	±20 V
	Max. signal delay	2 μs (rising edge)

(7). External Control Interface

Connector types	9-pin round connector x1; also used as synchronization control interface
Electrical specifications	Logic signal of 0 V/5 V (2.5 V to 5 V), or contact signal (shorted/open)
	Integration start, integration stop, data reset, event (the event set as the synchronization control function) Cannot be used at the same time as synchronization control.

Function Specifications -1. Control Functions

-1. Control Function	-1. Control Functions		
AUTO range function	Automatically selects voltage and current ranges according to measured amplitude on each phase. Operating states: Selectable on or off for each phase system Auto-ranging span: Wide/Narrow (common to all wiring systems)		
Timing control function	Interval OFF/50 ms/100 ms/200 ms/500 ms/1 s/5 s/10 s/ 15 s/30 s/1 min/5 min/10 min/15 min/30 min/60 min Setting determines the maximum data-saving capacity Timing controls OFF/Timer/RTC Timer 10 s to 9999:59:59 [h:m:s] (in seconds) Real-time clock : Start and stop times (in minutes)		
Hold function	Stops all updating of displayed measurement values and waveforms, and holds display. Internal calculations such as integration and averaging, clock, and peak-over display continue to be updated.		
Peak hold function	All measurement values are updated to display the maximum value for each measurement. Displayed waveforms and integration values continue to be updated with instantaneous values.		

-2. Calculation Functions

Scaling calculation	VT(PT) ratio and CT ratio: OFF/0.01 to 9999.99							
Average calculation	OFF/FAST/MID/SLOW/SLOW2/SLOW3 Exponentially averages all instantaneous measurement values including harmonics (but not peak, integration, or FFT noise values). Applied to displayed values and saved data. Response speed (time remains within specified accuracy when input changes from 0 to 100% f.s.) FAST: 0.2 s, MID: 1.0 s, SLOW: 5 s, SLOW2: 25 s, SLOW3: 100 s							
Efficiency and loss calculations								
Δ-Y calculation	For 3P3W3M systems, converts between line-to-line voltage and phase voltage waveforms using a virtual center point. All voltage parameters including harmonics such as true rms voltage are calculated as phase voltage waveforms. U1s = (U1s-U3s)/3, U2s = (U2s-U1s)/3, U3s = (U3s-U2s)/3							
Selecting the calculation method	TYPE1/TYPE2 (only valid when wiring is 3P3W3M) Select the calculation method used to calculate the apparent power and reactive power during 3P3W3M wiring. Only affect measurement values S123, Q123, ϕ 123, λ 123							
Current sensor phase correction calculations	Compensation by calculating the current sensor's harmonic phase characteristics Correction points are set using frequency and phase difference (set separately for each wiring mode). Frequency: 0.001 kHz to 999.999 kHz (in 0.001 kHz increments) Phase difference: 0.00 °. to ±90.00 °. (in 0.01 °. increments) However, the time difference calculated from the frequency phase difference is limited to a maximum of 200 us in 5 ns increments.							
2 Diaplay Functio								

-3. Display Functions Wiring Check screen The wiring diagram and voltage/current vectors are displayed for the selected

g	wiring system(s). The correct range for the wiring system is shown on the vector display, to confirm proper measurement cable connections.						
Independent wiring system display mode	Displays power and harmonic measurement values for channels 1 to 4. A composite measurement line pattern is displayed for each system. Basic, voltage, current, and power measurement parameter, harmonic bar graph, harmonic list, and harmonic vector screens						
Display Selections screen	Select to display any 4 Display layout: 4, 8, 16				arameters.		
Efficiency and Loss screen	The efficiency and los displayed numerically.				mulas are		
Waveform & Noise screen	Voltage and current waveforms sampled at 500 kHz and noise measurement are displayed compressed on one screen. Trigger: Synchronized with the harmonic sync source Recording length: 1000/5000/10,000/50,000 x All voltage and current chann Compression ratio: 1/1, 1/2, 1/5, 1/10, 1/20, 1/50 (peak-to-peak compression) Recording time:						
	Recording speed/ 1000 5000 10,000 50,000 Recording length						
	500 kS/s 2 ms 10 ms 20 ms 100 ms 250 kS/s 4 ms 20 ms 40 ms 200 ms 100 kS/s 10 ms 50 ms 100 ms 500 ms						
	50 kS/s 20 ms 100 ms 200 ms 1000 ms						
	25 kS/s 40 ms 200 ms 400 ms 2000 ms						
	10 kS/s	100 ms	500 ms	1000 ms	5000 ms		

Trend screen	Display a time-sequence graph of measured values for basic measurement parameters that have been selected as trend display parameters. Waveforms are graphed using peak-peak compression of data refresh rate data based on the time axis setting. Data is not stored. Number of graphed parameters: Up to 8 Time axis: 1.5 / 3 / 6 / 12 / 30 s/div.; 1 / 3 / 6 / 10 / 30 min./div.; 1 / 3 / 6 / 12 hour/div.; 1 day/div. Vertical axis: Auto (configured so that the data in the screen display range fits on the screen) / semi-auto (user selects the zoom factor relative to the full-scale values for graphed parameters from the following: 1/8, 1/4, 1/2, x1, x2, x5, x10, x50, x100, x200, x500) /manual (user sets the maximum and minimum values for the display)
X-Y Plot screen	Select horizontal and vertical axes from the basic measurement items to display on the X-Y graphs. Dots are plotted at the data update interval, and are not saved. Drawing data can be cleared. Horizontal: 1 data item (gauge display available), Vertical: 2 data items (gauge display available)

-4. Saving Functions

Auto-save function	As the items to be saved, select any measured values including harmonics and noise value data of the FFT function. The selected items are stored to CF card during every measurement interval. (Storage to USB memory is not available.) Can be controlled by timer or real-time clock. Max. no. of saved items: Interval-setting-dependent Data format: CSV format
Manual saving function	Save destinations: USB memory/CF card • Measurement data As the items to be saved, select any measured values including harmonics and noise value data of the FFT function. Pressing the SAVE key saves each measurement value at that moment to the save destination. File format: CSV format • Screen capture The COPY key captures and saves a bitmap image of the display to the save destination. *This function can be used at an interval of 5 sec or more while automatic saving is in progress. File format: Compressed BMP format Settings data Settings information can be saved/loaded as a settings file. File format: SET format (for PW3390 only) • Waveform data Saves the waveform being displayed by means of [Wave/Noise] display. File format: CSV format Save the noise measurement FFT spectrum shown on the Waveform/Noise screen.

-5. Synchronous Control Function

Function	Synchronous measurements are available by using sync cables to connect Model PW3390 (primary/secondary). When internal settings match, auto-save is available while synchronized.				
Synchronized items	Clock, data update interval (except for FFT calculations), integration start/stop, data reset, certain events				
Event items	Hold, manual save, screen capture				
Synchronization timing	Clock, data update interval Within 10 s after power-on by a secondary PW3390 Start/stop, data reset, event Upon key-press and communications operations on the primary PW3390				
Synchronization delay	Maximum 5 μs per connection. Maximum synchronization delay of an event is +50 ms				

-6. Bluetooth® Logger Connectivity

	Sends measured values wirelessly to logger by using a Bluetooth® serial conversion adapter.
Supported devices	Hioki LR8410 Link-compatible loggers (LR8410, LR8416)
Sent data	Measured values assigned to the D/A CH9 to CH16 analog output parameters

-7. Other Functions

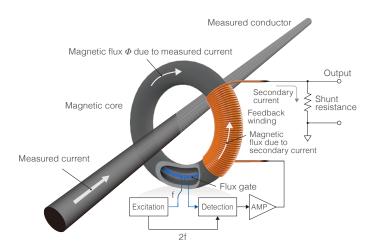
-7. Other runctions					
Display language selection	Japanese, English, Chinese				
Beep sound	OFF/ON				
Screen color schemes	COLOR1 (black)/2 (blue-green)/3 (blue)/4 (gray)/5 (navy blue)				
Start-up screen selection	Wiring or Last-displayed screen (Measurement screens only)				
LCD backlight	ON/1 min/5 min/10 min/30 min/60 min				
CSV file format	CSV/SSV				
Real-time clock function	Auto-calendar, leap-year correcting 24-hour clock				
RTC accuracy	±3 s per day @25°C (77°F)				
Sensor recognition	Current sensors are automatically recognized when connected (Excluding the CT7000 series sensors)				
Warning indicators	When peak over occurs on voltage and current measurement channels, When no sync source is detected Warning indicators for all channels are displayed on all pages of the MEAS screen.				
Key-lock	Toggles on/off by holding the ESC key for three seconds.				
System reset	Returns all settings to factory defaults				
Power-on reset	Returns all settings including language and communications settings, to factory defaults.				
File operations	Media content list display, format media, create folders, delete files and folders, copy between storage media				

General Specifications

Operating environment	Indoors, Pollution Degree 2, altitude up to 2000 m (6562.20 ft)				
Operating temperature and humidity	Temperature: -10°C to 40°C (14°F to 104°F), Humidity: 80% RH or less (no condensation)				
Storage temperature and humidity	-10°C to 50°C (14°F to 122°F), 80% RH or less (no condensation)				
Dustproof and waterproof	IP20 (EN 60529)				
Applicable standards	Safety EN 61010 EMC EN 61326 Class A				
Power supply	100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V				
Backup battery life	Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F)				
Dimensions	340 mm (13.39 in) W x 170 mm (6.69 in) H x 156 mm (6.14 in) D (excluding protrusions)				
Mass	4.6 kg (162.3 oz) with PW3390-03				
Product warranty period	3 year				
Accessories	Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m (2.95 ft)) ×1, Input cord label ×2, D-sub connector ×1 (PW3390-02, PW3390-03)				

Introduction to Current Sensors Designed for High-accuracy Measurement

Technology that Supports the Evolution of Current Testing



High-frequency currents are detected by a winding (CT), while DC to low-frequency currents are detected by a flux gate.

Excellent S/N (signal to noise) ratio at low frequencies Hall element detection Frequency Excellent S/N (signal to noise) ratio at high frequencies winding (CT) detection Frequency

Zero-flux method: achieving stable, wideband measurement from DC to high frequencies

High-accuracy sensors use the "zero flux method (flux gate detection type)" as the measurement method. High-frequency currents are detected with the winding (CT method), and DC to low frequency currents are detected using a "flux gate."

Flux gate detection

Flux gate detection delivers excellent linearity and can measure currents across a wide range of magnitudes with a high degree of accuracy.

The flux gate component, used in DC detection, has extremely small offset in a wide range of temperatures due to its operating principle and therefore achieves high precision and superior stability. Ideal for measurements that require high accuracy using instruments such as power analyzers and power meters. Highly applicable

for testing inverter efficiency, inverter output power, reactor or transformer loss, as well as long-term DC measurements.

Flat characteristics from low to high frequencies Zero-flux method Hall element detection winding (CT) detection Frequency

Zero-flux method (flux gate) current sensors



CT6841A, CT6843A CT6844A









CT6904A

CT6875A CT6876A

CT6862, CT6863 CT6872, CT6873

Clamp types

Clamp-type sensors are quick and easy to connect, and used for testing finished products, an application where it is difficult to cut wires. Capable of functioning at temperatures from -40°C to 85°C, they're used in high-temperature environments such as engine compartments.





WLTP-compliant fuel economy (electricity cost) performance testing

Pass-through types

Pass-through sensors deliver the ultimate level of accuracy and stability. With a broadband measurement at up to 10 MHz and measurement of large currents of up to 2000 A, they're used in state-of-the-art research and development.





EV inverter system R&D

Evaluation of reactor and transformer losses

¹⁶ Current sensors High accuracy clamp

		CT6846A	CT6845A	CT6844A	
Appearance		NEW	NEW	NEW	
R	ated current	1000 A AC/DC	500 A AC/DC	500 A AC/DC	
Fr	equency band	DC to 100 kHz	DC to 200 kHz	DC to 500 kHz	
Di	ameter of measurable conductors	Max. φ 50 mm (1.97 in.)	Max. φ 50 mm (1.97 in.)	Max. φ 20 mm (0.79 in.)	
		DC : ±0.25% ±0.09%	DC : ±0.25% ±0.09%	DC : ±0.25% ±0.09%	
	Current (I) PW3390	45 Hz ≤ f ≤ 66 Hz : ±0.24% ±0.07%	45 Hz ≤ f ≤ 66 Hz : ±0.24% ±0.07%	45 Hz ≤ f ≤ 66 Hz : ±0.24% ±0.07%	
	Combined*1	DC : ±0.25% ±0.09%	DC : ±0.25% ±0.09%	DC : ±0.25% ±0.09%	
	Active power (P)	45 Hz ≤ f ≤ 66 Hz : ±0.24% ±0.07%	45 Hz ≤ f ≤ 66 Hz : ±0.24% ±0.07%	45 Hz ≤ f ≤ 66 Hz : ±0.24% ±0.07%	
		DC : ±0.2% ±0.02%	DC : ±0.2% ±0.02%	DC : ±0.2% ±0.02%	
ç		DC < f ≤ 100 Hz : ±0.2% ±0.01%	DC < f ≤ 100 Hz : ±0.2% ±0.01%	DC < f ≤ 100 Hz : ±0.2% ±0.01%	
Accuracy	Sensor only (amplitude) ±(% of reading +% of full scale) full scale is rated current of sensor	100 Hz < f ≤ 500 Hz : ±0.5% ±0.02%	100 Hz < f ≤ 500 Hz : ±0.3% ±0.02%	100 Hz < f ≤ 500 Hz : ±0.3% ±0.02%	
400		500 Hz < f ≤ 1 kHz : ±1.0% ±0.02%	500 Hz < f ≤ 1 kHz : ±0.5% ±0.02%	500 Hz < f ≤ 1 kHz : ±0.5% ±0.02%	
_		1 kHz < f ≤ 5 kHz : ±2.0% ±0.02%	1 kHz < f ≤ 5 kHz : ±1.0% ±0.02%	1 kHz < f ≤ 5 kHz : ±1.0% ±0.02%	
		5 kHz < f ≤ 10 kHz : ±5% ±0.02%	5 kHz < f ≤ 10 kHz : ±1.5% ±0.02%	5 kHz < f ≤ 10 kHz : ±1.5% ±0.02%	
		10 kHz < f ≤ 50 kHz : ±30% ±0.02%	10 kHz < f ≤ 20 kHz : ±5% ±0.02%	10 kHz < f ≤ 50 kHz : ±5.0% ±0.02%	
		_	20 kHz < f ≤ 50 kHz : ±10% ±0.05%	50 kHz < f ≤ 100 kHz : ±15% ±0.05%	
		_	50 kHz < f ≤ 100 kHz : ±30% ±0.05%	100 kHz < f ≤ 300 kHz : ±30% ±0.05%	
0	perating Temperature	-40°C to 85°C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)	
М	aximum rated voltage to earth	CATIII 1000 V	CATIII 1000 V	CATIII 1000 V	
_		238 (9.37") W × 116 (4.57") H × 35 (1.38") D mm	238 (9.37") W × 116 (4.57") H × 35 (1.38") D mm	153 (6.02") W × 67 (2.64") H × 25 (0.98") D mm	
D	mensions	Cable length: 3 m (9.84 ft)	Cable length: 3 m (9.84 ft)	Cable length: 3 m (9.84 ft)	
М	ass	Approx. 990 g (34.9 oz)	Approx. 860 g (30.3 oz)	Approx. 400 g (14.1 oz)	
Di	erating properties	1800	1000	800	

*1 ±(% of reading + % of range), range is PW3390 CT6846A: Add ±0.15% of the range for 10 A range or 20 A range. CT6844A: Add ±0.15% of the range for 10 A range or 20 A range.

Custom cable lengths also available. Please inquire with your Hioki distributor.

		СТ	6843A	СТ	6841A	92	9272-05	
Appearance		NEW		NEW				
Rated current		200 /	A AC/DC	20 A	20 A AC/DC		200 A/20 A AC switching	
Frequency ba	nd	DC to	500 kHz	DC t	o 1 MHz	1kHz	to 100 kHz	
Diameter of me	asurable conductors	Мах. ф 20	mm (0.79 in.)	Max. φ 20	mm (0.79 in.)	Max. φ 46	6 mm (1.81 in.)	
PW3390 Combined	Current (I) Active power (P)	DC 45 Hz ≤ f ≤ 66 Hz DC 45 Hz ≤ f ≤ 66 Hz	: ±0.25% ±0.09% DC z ≤ f ≤ 66 Hz : ±0.24% ±0.07% 45 Hz ≤ f ≤ : ±0.25% ±0.09% DC		: ±0.25% ±0.12% : ±0.24% ±0.07% : ±0.25% ±0.12% : ±0.24% ±0.07%	PW3390 accuracy + Sensor accuracy		
		DC	: ±0.2% ±0.02%	DC	: ±0.2% ±0.05%		_	
		DC < f ≤ 100 Hz	: ±0.2% ±0.01%	DC < f ≤ 100 Hz	: ±0.2% ±0.01%	1 Hz ≤ f < 5 Hz	: ±2.0% ±0.10%	
2		100 Hz < f ≤ 500 Hz	: ±0.3% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.3% ±0.02%	5 Hz ≤ f < 10 Hz	: ±1.0% ±0.05%	
Sensor on		500 Hz < f ≤ 1 kHz	: ±0.5% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.5% ±0.02%	10 Hz ≤ f < 45 Hz	: ±0.5% ±0.02%	
Sensor onl	y (amplitude)	1 kHz < f ≤ 5 kHz	: ±1.0% ±0.02%	1 kHz < f ≤ 5 kHz	: ±1.0% ±0.02%	45 Hz < f ≤ 66 Hz	: ±0.3% ±0.01%	
±(% of readi	ng +% of full scale)	5 Hz < f ≤ 10 kHz	: ±1.5% ±0.02%	5 Hz < f ≤ 10 kHz	: ±1.5% ±0.02%	66 Hz < f ≤ 1 kHz	: ±0.5% ±0.02%	
full scale is r	ated current of sensor	10 kHz < f ≤ 50 kHz	: ±5.0% ±0.02%	10 kHz < f ≤ 50 kHz	: ±2.0% ±0.02%	1 kHz < f ≤ 5 kHz	: ±1.0% ±0.05%	
		50 kHz < f ≤ 100 kHz	: ±15% ±0.05%	50 kHz < f ≤ 100 kHz	: ±5.0% ±0.05%	5 kHz < f ≤ 10 kHz	: ±2.5% ±0.10%	
		100 kHz < f ≤ 300 kHz	: ±15% ±0.05%	100 kHz < f ≤ 300 kHz	: ±10% ±0.05%	10 kHz < f ≤ 50 kHz	: ±5.0% ±0.10%	
		300 kHz < f ≤ 500 kHz	: ±30% ±0.05%	300 kHz < f ≤ 500 kHz	: ±15% ±0.05%	50 kHz < f ≤ 100 kHz	: ±30.0% ±0.10%	
			_	500 kHz < f < 1 MHz	: ±30% ±0.05%		_	
Operating Ten	perature	-40°C to 85°C (-40°F to 185°F)		-40°C to 85°C (-40°F to 185°F)		0°C to 50°C (32°F to 122°F)		
Maximum rate	d voltage to earth	CATI	II 1000 V	CATIII 1000 V		CATIII A	AC600 V rms	
Dimensions			64") H × 25 (0.98") D mm th: 3 m (9.84 ft)	153 (6.02") W × 67 (2.64") H × 25 (0.98") D mm Cable length: 3 m (9.84 ft)		78 (3.07") W × 188 (7.40") H × 35 (1.38") D mm Cable length: 3 m (9.84 ft)		
Mass	Approx. 370 g (13.1 oz)		Approx. 350 g (12.3 oz)		Approx. 450 g (15.9 oz)			
Derating properties		E 450 440 A √ 4 400 A √ 4 4 4 4 400 A √ 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4				400		

 $^{^{*2}}$ \pm (% of reading + % of range) , range is PW3390 CT6843A: Add \pm 0.15% of the range for 0.4 A range or 8 A range. CT6841A: Add \pm 0.15% of the range for 0.4 A range or 0.8 A range.

Custom cable lengths also available. Please inquire with your Hioki distributor.

Current sensors High accuracy pass-through

_								
		CT6877A, CT6877A-1*4		CT6876A,	CT6876A-1*4	CT6904A-2, CT6904A-3*4		
Appearance		NEW		NEW		NEW Build-to-order product CT6904A-2 CT6904A-3		
F	ated current		2000	A AC/DC	1000	A AC/DC	800 A	AC/DC
F	requency band	d	DC t	o 1 MHz		DC to 1.5 MHz : DC to 1.2 MHz		:: DC to 4 MHz :: DC to 2 MHz
D	iameter of meas	urable conductors	Max. φ 80	mm (3.14 in.)	Max. φ 36	6 mm (1.42 in.)	Max. φ 32	mm (1.25 in.)
		0	DC	: ±0.09% ±0.078%	DC	: ±0.09% ±0.078%		
	PW3390	Current (I)	45 Hz ≤ f ≤ 66 Hz	: ±0.08% ±0.058%	45 Hz ≤ f ≤ 66 Hz	: ±0.08% ±0.058%	DW0000	0
	Combined*3	Active power (P)	DC	: ±0.09% ±0.078%	DC	: ±0.09% ±0.078%	PW3390 accurac	y + Sensor accuracy
		Active power (P)	45 Hz ≤ f ≤ 66 Hz	: ±0.08% ±0.058%	45 Hz ≤ f ≤ 66 Hz	: ±0.08% ±0.058%		
			DC	: ±0.04% ±0.008%	DC	: ±0.04% ±0.008%	DC	: ±0.030% ±0.009%
			DC < f < 16 Hz	: ±0.1% ±0.02%	DC < f < 16 Hz	: ±0.1% ±0.02%	DC < f < 16 Hz	: ±0.2% ±0.025%
>			16 Hz ≤ f < 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 45 Hz	: ±0.1% ±0.025%
ccuracy			45 Hz ≤ f ≤ 66 Hz	: ±0.04% ±0.008%	45 Hz ≤ f ≤ 66 Hz	: ±0.04% ±0.008%	45 Hz ≤ f ≤ 65 Hz	: ±0.025% ±0.009%
CCU	Sensor only (Sensor only (amplitude) ±(% of reading +% of full scale)	66 Hz < f ≤ 100 Hz	: ±0.05% ±0.01%	66 Hz < f ≤ 100 Hz	: ±0.05% ±0.01%	65 Hz < f ≤ 850 Hz	: ±0.05% ±0.009%
⋖	0011001 01119 (100 Hz < f ≤ 500 Hz	: ±0.1% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.1% ±0.02%	850 Hz < f ≤ 1 kHz	: ±0.1% ±0.013%
	, ,	ed current of sensor	500 Hz < f ≤ 1 kHz	: ±0.2% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.2% ±0.02%	1 kHz < f ≤ 5 kHz	: ±0.4% ±0.025%
	Tuli Soulo is rate	d carrent or sensor	1 kHz < f ≤ 10 kHz	: ±0.5% ±0.02%	1 kHz < f ≤ 5 kHz	: ±0.5% ±0.02%	5 kHz < f ≤ 10 kHz	: ±0.4% ±0.025%
			10 kHz < f ≤ 50 kHz	: ±1.5% ±0.05%	5 kHz < f ≤ 10 kHz	: ±0.5% ±0.02%	10 kHz < f ≤ 50 kHz	: ±1% ±0.025%
			50 kHz < f ≤ 100 kHz	: ±2.5% ±0.05%	10 kHz < f ≤ 50 kHz	: ±2.0% ±0.05%	50 kHz < f ≤ 100 kHz	: ±1.0% ±0.063%
			100 kHz < f ≤ 700 kHz	: ±(0.025×f kHz)% ±0.05%	50 kHz < f ≤ 100 kHz	: ±3.0% ±0.05%	100 kHz < f ≤ 300 kHz	: ±2.0% ±0.063%
				_	100 kHz < f ≤ 1 MHz	: ±(0.03×f kHz)% ±0.05%	300 kHz < f ≤ 1 MHz	: ±5.0% ±0.063%
C	perating Temp	erature	-40°C to 85°C	C (-40°F to 185°F)	-40°C to 85°C	C (-40°F to 185°F)	-10°C to 50°C	(-14°F to 122°F)
N	faximum rated	voltage to earth	CATI	II 1000 V	CATIII 1000 V		CATIII 1000 V	
D	imensions			9.13") × 112D (4.41") mm 9.84 ft), CT6877A-1:10 m (32.81 ft)]	160W (6.30") × 112H (4.41") × 50D (1.97") mm Cable length [CT6876A: 3 m (9.84 ft), CT6876A-1:10 m (32.81 ft)]		139W (5.47") × 120H (4.72") × 52D (2.05") mm Cable length [CT6904A-2: 3 m (9.84 ft), CT6904A-3:10 m (32.81 ft)]	
N	lass		Approx. 5 kg (176.4 oz.),	Approx. 5.3 kg (187.0 oz.)*4	Approx. 970 g (34.2 oz.)	, Approx. 1300 g (45.9 oz.) *4	Approx. 1150 g (40.6 oz.), Approx. 1450 g (51.1 oz.) *4	
		Frequency derating		Frequency derating		Fre	quency derating	
Derating properties		ties	1 1 1 1 1 1 1 1 1 1	C(140°F) (continuous)	10 10 10 10 10 10 10 10 10 10 10 10 10 1		1	

^{*3 ±(%} of reading + % of range), range is PW6001
CT6877A/CT6877A-1: Add ±0.15% of the range for 40 A range or 80 A range; CT6876A/CT6876A-1: Add ±0.15% of the range for 20 A range or 40 A range.

*4 The CT6877A-1, CT6876A-1, and CT6904A-3 have a 10 m cord. For the CT6877A-1, add ±(0.005 × f kHz)% of reading for amplitude accuracy and ±(0.015 × f kHz)° for phase accuracy for frequencies of 1 kHz < f ≤ 700 kHz. For the CT6876A-1, add ±(0.005 × f kHz)% of reading for amplitude accuracy for frequencies of 1 kHz < f ≤ 1 MHz.

For the CT6904A-3, add ±(0.015 × f kHz)% of reading for amplitude accuracy for frequencies of 50 kHz < f ≤ 1 MHz.

		CT6904A, CT6904A-1*6		CT6875A, CT6875A-1*6		CT6873, CT6873-01*6	
Appearance		NEW Build-to-order product CT 6904A-1 Wideband 4 MHz		NEW		NEW Wideband 10 MHz	
Ra	ated current	500	A AC/DC	500	A AC/DC	200	A AC/DC
Fr	equency band		: DC to 4 MHz 1: DC to 2 MHz		: DC to 2 MHz : DC to 1.5 MHz	DC	to 10 MHz
Di	ameter of measurable conductors	Мах. ф 32	mm (1.25 in.)	Max. φ 36	6 mm (1.42 in.)	Мах. ф 2	24 mm (0.94 in.)
	PW3390 Combined*5 Active power (P)	PW3390 accura	cy + Sensor accuracy	DC 45 Hz ≤ f ≤ 66 Hz DC	: ±0.09% ±0.078% : ±0.08% ±0.058% : ±0.09% ±0.078%	DC 45 Hz ≤ f ≤ 66 Hz DC	: ±0.08% ±0.072% : ±0.07% ±0.057% : ±0.08% ±0.072%
				45 Hz ≤ f ≤ 66 Hz	: ±0.08% ±0.058%	45 Hz ≤ f ≤ 66 Hz	: ±0.07% ±0.057%
		DC C 1011	: ±0.025% ±0.007%	DC C 4011	: ±0.04% ±0.008%	DC C () () ()	: ±0.03% ±0.002%
		DC < f < 16 Hz	: ±0.2% ±0.02%	DC < f < 16 Hz	: ±0.1% ±0.02%	DC < f ≤ 16 Hz	: ±0.1% ±0.01%
5	Sensor only (amplitude)	16 Hz ≤ f < 45 Hz 45 Hz ≤ f ≤ 65 Hz	: ±0.1% ±0.02% : ±0.02% ±0.007%	16 Hz ≤ f < 45 Hz 45 Hz ≤ f ≤ 66 Hz	: ±0.05% ±0.01% : ±0.04% ±0.008%	16 Hz < f ≤ 45 Hz 45 Hz < f ≤ 66 Hz	: ±0.05% ±0.01%
Accuracy		45 Hz < f ≤ 850 Hz	: ±0.02% ±0.007%	45 Hz ≤ f ≤ 100 Hz	: ±0.04% ±0.006%	45 Hz < f ≤ 100 Hz	: ±0.03% ±0.007% : ±0.04% ±0.01%
Acc		850 Hz < f ≤ 1 kHz	: ±0.1% ±0.01%	100 Hz < f ≤ 500 Hz	: ±0.05% ±0.01%	100 Hz < f ≤ 500 Hz	: ±0.04% ±0.01%
	±(% of reading +% of full scale)	1 kHz < f ≤ 5 kHz	: ±0.1% ±0.01%	500 Hz < f ≤ 1 kHz	: ±0.1% ±0.02%	500 Hz < f ≤ 3 kHz	: ±0.05% ±0.01%
	full scale is rated current of sensor	5 kHz < f ≤ 10 kHz	: ±0.4% ±0.02%	1 kHz < f ≤ 5 kHz	: ±0.4% ±0.02%	3 kHz < f ≤ 5 kHz	: ±0.1% ±0.01%
		10 kHz < f ≤ 50 kHz	: ±1.0% ±0.02%	5 kHz < f ≤ 10 kHz	: ±0.4% ±0.02%	5 kHz < f ≤ 10 kHz	: ±0.2% ±0.02%
		50 kHz < f ≤ 100 kHz	: ±1.0% ±0.05%	10 kHz < f ≤ 50 kHz	: ±1.5% ±0.05%	10 kHz < f ≤ 1 MHz	: ±(0.018×f kHz)% ±0.05%
		100 kHz < f ≤ 300 kHz	: ±2.0% ±0.05%	50 kHz < f ≤ 100 kHz	: ±2.5% ±0.05%	101012 (12 11012	_
		300 kHz < f ≤ 1 MHz	: ±5.0% ±0.05%	100 kHz < f ≤ 1 MHz	: ±(0.025×f kHz)% ±0.05%		_
0	perating Temperature	-10°C to 50°C (-14°F to 122°F)		-40°C to 85°C (-40°F to 185°F)		-40°C to 85°C (-40°F to 185°F)	
_	aximum rated voltage to earth		II 1000 V		III 1000 V		TIII 1000 V
	mensions	139W (5.47") × 120H	(4.72") × 52D (2.05") mm 9.84 ft), CT6904A-1:10 m (32.81 ft)]	160W (6.30") × 112H (4.41") × 50D (1.97") mm Cable length [CT6875: 3 m (9.84 ft), CT6875A-1:10 m (32.81 ft)]		70W (2.76") × 110H (4.33") × 53D (2.09") mm Cable length [CT6873: 3 m (9.84 ft), CT6873-01:10 m (32.81 ft)]	
M	ass	Approx. 1.05kg (37.0 oz.)	, Approx. 1.35 kg (47.6 oz.) *6	Approx. 820 g (28.9 oz.), Approx. 1150 g (40.6 oz.) *6		Approx. 370 g (13.1 oz.), Approx. 690 g (24.3 o.z) *6	
De	erating properties	Frequency derating Food A Fo		Frequency denating Frequency denating Frequency denating 100		Frequency derating	

^{*5 ±(%} of reading + % of range), range is PW3390

CT6875A/CT6875A-1: Add ±0.15% of the range for 10 A range or 20 A range; CT6873/CT6873-01: Add ±0.15% of the range for 4 A range or 8 A range.

*6 The CT6904A-1, CT6875A-1, and CT6873-01 have a 10 m cord. For the CT6904A-1, add ±(0.015 x f kHz)% of reading for amplitude accuracy for frequencies of 50 kHz < f ≤ 1 MHz.

For the CT6873-01, add ±(0.005 x f kHz)% of reading for amplitude accuracy and ±(0.015 x f kHz)° for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz.

For the CT6873-01, add ±(0.015 x f kHz)° for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz.

		CT6863-05		CT6872, CT6872-01*8		CT6862-05	
Appearance				Wideband 10 MHz			
F	ated current	200 A AC/DC		50 A AC/DC		50 A AC/DC	
F	requency band	DC to 500 kHz		DC to 10 MHz		DC to 1 MHz	
	iameter of measurable conductors	Max. φ 24	mm (0.94 in.)	Max. φ 2	4 mm (0.94 in.)	Max. φ 24 mm (0.94 in.)	
	PW3390 Combined*7 Active power (P)	PW3390 accurac	cy + Sensor accuracy	DC 45 Hz ≤ f ≤ 66 Hz DC 45 Hz ≤ f ≤ 66 Hz	: ±0.08% ±0.072% : ±0.07% ±0.057% : ±0.08% ±0.072% : ±0.07% ±0.057%	PW3390 accurad	cy + Sensor accuracy
		DC	: ±0.05% ±0.01%	DC	: ±0.03% ±0.002%	DC	: ±0.05% ±0.01%
		DC < f ≤ 16 Hz	: ±0.10% ±0.02%	DC < f ≤ 16 Hz	: ±0.1% ±0.01%	DC < f ≤ 16 Hz	: ±0.10% ±0.02%
5	Sensor only (amplitude) ±(% of reading +% of full scale) full scale is rated current of sensor	16 Hz ≤ f < 400 Hz	: ±0.05% ±0.01%	16 Hz < f ≤ 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 400 Hz	: ±0.05% ±0.01%
ccuracy		400 Hz ≤ f ≤ 1 kHz	: ±0.2% ±0.02%	45 Hz < f ≤ 66 Hz	: ±0.03% ±0.007%	400 Hz ≤ f ≤ 1 kHz	: ±0.2% ±0.02%
Acc		1 kHz < f ≤ 5 kHz	: ±0.7% ±0.02%	66 Hz < f ≤ 100 Hz	: ±0.04% ±0.01%	1 kHz < f ≤ 5 kHz	: ±0.7% ±0.02%
		5 kHz < f ≤ 10 kHz	: ±1.0% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.06% ±0.01%	5 kHz < f ≤ 10 kHz	: ±1.0% ±0.02%
		10 kHz < f ≤ 50 kHz	: ±2.0% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.1% ±0.01%	10 kHz < f ≤ 50 kHz	: ±1.0% ±0.02%
		50 kHz < f ≤ 100 kHz	: ±5.0% ±0.05%	1 kHz < f ≤ 5 kHz	: ±0.15% ±0.02%	50 kHz < f ≤ 100 kHz	: ±2.0% ±0.05%
		100 kHz < f ≤ 300 kHz	: ±10% ±0.05%	5 kHz < f ≤ 10 kHz	: ±0.15% ±0.02%	100 kHz < f ≤ 300 kHz	: ±5.0% ±0.05%
		$300 \text{ kHz} < \text{f} \le 500 \text{ kHz}$: ±30% ±0.05%	10 kHz < f ≤ 1 MHz	: ±(0.012×f kHz)% ±0.05%	300 kHz < f ≤ 700 kHz	: ±10% ±0.05%
					_	700 kHz < f < 1 MHz	: ±30% ±0.05%
C	perating Temperature	-30°C to 85°C (-22°F to 185°F)		-40°C to 85°C (-40°F to 185°F), 80% RH or less		-30°C to 85°C (-22°F to 185°F)	
N	laximum rated voltage to earth	CATI	II 1000 V	CATIII 1000 V		CATIII 1000 V	
D	imensions		3.94") × 53D (2.09") mm oprox. 3 m (9.84 ft.)	70W (2.76") × 110H (4.33") × 53D (2.09") mm Cable length [CT6872: 3 m (9.84 ft), CT6872-01:10 m (32.81 ft)]		70W (2.76") × 100H (3.94") × 53D (2.09") mm Cable length: Approx. 3 m (9.84 ft.)	
N	lass	Approx. 350 g (12.3 oz.)		Approx. 370 g (13.1 oz.), Approx. 690 g (24.3 o.z) *8		Approx. 340 g (12.0 oz.)	
С	erating properties	Frequency derating Frequency derating Frequency derating Frequency derating Frequency derating		Frequency derating Frequency derating		Frequency derating Frequency derating Frequency derating Frequency derating	

 $^{^{\}star7}$ ±(% of reading + % of range) , range is PW3390

Custom cable lengths also available. Please inquire with your Hioki distributor.

Standard Sensor

CT9920 (sold separately) is required to connect PW3390 to the sensor with HIOKI PL14 on the output connector.

	AC/DC CURRENT SENSOR CT7642 AC/DC AUTO ZERO CURRENT SENSOR CT7742	AC FLEXIBLE CURRENT SENSOR CT7044, CT7045, CT7046		
Appearance	8181			
Rated current	2000 A AC/DC	6000 A AC		
Frequency band	CT7642: DC to 10 kHz CT7742: DC to 5 kHz	10 Hz to 50 kHz (±3 dB)		
Diameter of measurable conductors	ф 55 mm (2.17 in) or less	CT7044: φ 100 mm (3.94 in) or less CT7045: φ 180 mm (7.09 in) or less CT7046: φ 254 mm (10.00 in) or less		
Basic accuracy	For DC, 45 Hz to 66 Hz Amplitude: ±1.5% rdg. ±0.5% f.s. For up to 66 Hz Phase: ±2.3 °	For 45 to 66 Hz, with flexible cable core Amplitude: ±1.5% rdg. ±0.25% f.s. Phase:±1.0 °		
Frequency characteristics (Amplitude) 66 Hz to 1 kHz ±2.5% rdg. ±1.0% f.s.		-		
Operating temperature	-25°C to 65°C (-13°F to 149°F)	-25°C to 65°C (-13°F to 149°F)		
Effect of conductor position	±1.0% rdg. or less	±3.0% or less		
Effect of external magnetic fields	In 400 A/m magnetic field (DC) 0.2% f.s. or less	In 400 A/m magnetic field (50 Hz/60 Hz) CT7044, CT7045: 1.25% f.s. or less CT7046: 1.5% f.s. or less		
Output connector	HIOKI PL14*	HIOKI PL14*		
Dimensions	64 mm (2.52 in) W x 195 mm (7.68 in) H x 34 mm (1.34 in) D Cable length: 2.5 m (8.20 ft)	Circuit box: 25 mm (0.98 in) W x 72 mm (2.83 in) H x 20 mm (0.79 in) D Cable length: 2.5 m (8.20 ft)		
Mass	510 g (18.0 oz)	CT7044: 160 g (5.6 oz) CT7045: 174 g (6.1 oz) CT7046: 186 g (6.6 oz)		
Derating properties	2.5 k 2.5 k 2.5 k 2.5 k 2.5 k 2.5 k 3.5 k 3.5 k 3.5 k 3.5 k 4.5 k 4.	12 k 10 k 10 k 10 100 1 k 10 k 100 k Frequency [Hz]		

High Accuracy Sensor, Direct Wire Type

Newly developed DCCT method allows world-class measurement range and measurement accuracy at a rating of 50 A. (5 A rating version also available. Please inquire with your Hioki distributor.)

	AC/DC CURRENT BOX PW9100A-3	AC/DC CURRENT BOX PW9100A-4		
Appearance	in in in			
Number of input channels	3ch	4ch		
Rated current	50 A AC/DC			
Frequency band	DC to 3.5 MHz (-3 dB)			
Basic accuracy	For 45 Hz to 65 Hz [Amplitude]: ±0.02% rdg. ±0.005% f.s. Phase: ±0.1 ° For DC [Amplitude]: ±0.02% rdg. ±0.007% f.s.			
Maximum rated voltage to earth	CATII 1000 V, CATIII 600 V			
Maximum rated	For DC [Amplitude]: ±0.02% rdg. ±0.007% f.s.			

PW3390 Combined

±(% of reading + % of range), range is PW3390

	Current (I)	Active power (P)	
DC	±0.07% ±0.077%	±0.07% ±0.077%	
45 Hz ≤ f ≤ 66 Hz	±0.06% ±0.055%	±0.06% ±0.055%	

Add ±0.12% of range for 1 A range or 2 A range.

Scan the QR code to view the PW9100A website product page.



Current Summing

SENSOR UNIT CT9557

Merges up to four current sensor output waveforms on a single channel, for output to PW6001.



Scan the QR code to view the CT9557 website product page.





Summed waveform output (CT9904 connected)

* CT9904 (sold separately) is required to connect to PW3390.

CT6873/(T6873-01: 40d ±0.15% of the range for 1 A range or 2 A range. ** The CT6872-01 has a 10 m cord. For the CT6872-01, add $\pm (0.015 \times f \text{ kHz})^{\circ}$ for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz.

Model: POWER ANALYZER PW3390

Model No. (Order Code)	D/A output	Motor analysis
PW3390-01	_	-
PW3390-02	0	-
PW3390-03	0	0

Accessories: Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable ×1, Input cord label ×2, D-sub 25-pin connector ×1 (PW3390-02, PW3390-03)

- $\bullet \ \, \text{The separately sold voltage cord and current sensor are required for taking measurements}. \\$
- Specify the number of built-in channels and whether to include the Motor Analysis & D/A Output upon order for factory installation. Please contact your local Hioki sales subsidiary or branch for changes after shipment.



Current measurement options (High accuracy: clamp type)

Model No. (Order Code)	Model	Rated current	Frequency band	Cable length
CT6846A	AC/DC CURRENT PROBE	1000 A rms	DC to 100 kHz	3 m
CT6845A	AC/DC CURRENT PROBE	500 A rms	DC to 200 kHz	3 m
CT6844A	AC/DC CURRENT PROBE	500 A rms	DC to 500 kHz	3 m
CT6843A	AC/DC CURRENT PROBE	200 A rms	DC to 700 kHz	3 m
CT6841A	AC/DC CURRENT PROBE	20 A rms	DC to 2 MHz	3 m
9272-05	CLAMP ON SENSOR	20 A/200 A rms AC	1 Hz to 100 kHz	3 m

Current measurement options (High accuracy: pass-through, direct connection type)

Model No. (Order Code)	Model	Rated current	Frequency band	Number of channels Cable length
CT6877A	AC/DC CURRENT SENSOR	2000 A rms	DC to 1 MHz	3 m
CT6877A-1	AC/DC CURRENT SENSOR	2000 A rms	DC to 1 MHz	10 m
CT6876A	AC/DC CURRENT SENSOR	1000 A rms	DC to 1.5 MHz	3 m
CT6876A-1	AC/DC CURRENT SENSOR	1000 A rms	DC to 1.2 MHz	10 m
CT6904A-2*	AC/DC CURRENT SENSOR	800 A rms	DC to 4 MHz	3 m
CT6904A-3*	AC/DC CURRENT SENSOR	800 A rms	DC to 2 MHz	10 m
CT6904A	AC/DC CURRENT SENSOR	500 A rms	DC to 4 MHz	3 m
CT6904A-1*	AC/DC CURRENT SENSOR	500 A rms	DC to 2 MHz	10 m
CT6875A	AC/DC CURRENT SENSOR	500 A rms	DC to 2 MHz	3 m
CT6875A-1	AC/DC CURRENT SENSOR	500 A rms	DC to 1.5 MHz	10 m
CT6873	AC/DC CURRENT SENSOR	200 A rms	DC to 10 MHz	3 m
CT6873-01	AC/DC CURRENT SENSOR	200 A rms	DC to 10 MHz	10 m
CT6863-05	AC/DC CURRENT SENSOR	200 A rms	DC to 500 kHz	3 m
CT6872	AC/DC CURRENT SENSOR	50 A rms	DC to 10 MHz	3 m
CT6872-01	AC/DC CURRENT SENSOR	50 A rms	DC to 10 MHz	10 m
CT6862-05	AC/DC CURRENT SENSOR	50 A rms	DC to 1 MHz	3 m
PW9100A-3	AC/DC CURRENT BOX	50 A rms	DC to 3.5 MHz	3 ch
PW9100A-4	AC/DC CURRENT BOX	50 A rms	DC to 3.5 MHz	4 ch

^{*} Build-to-order product

Current measurement options (Standard Sensor)

Carrott model official (ciandard censor)					
Model No. (Order Code)	Model	Rated current	Frequency band	Cable length	
CT7742**	AC/DC AUTO ZERO CURRENT SENSOR	2000 A rms	DC to 5 kHz	2.5 m	
CT7642**	AC/DC CURRENT SENSOR	2000 A rms	DC to 10 kHz	2.5 m	
CT7044**	AC FLEXIBLE CURRENT SENSOR (φ 100 mm (3.94 in))	6000 A rms	10 Hz to 50 kHz	2.5 m	
CT7045**	AC FLEXIBLE CURRENT SENSOR (φ 180 mm (7.09 in))	6000 A rms	10 Hz to 50 kHz	2.5 m	
CT7046**	AC FLEXIBLE CURRENT SENSOR (\$\phi\$ 254 mm (10.00 in))	6000 A rms	10 Hz to 50 kHz	2.5 m	

^{**} CONVERSION CABLE CT9920 is required to connect to the PW3390.

CONVERSION CABLE CT9900



Required to connect PW3390 to the current sensor with HIOKI PL23 on the output connector.

[Applicable products] CT6841, CT6843, CT6844, CT6845, CT6846, CT6862, CT6863, 9272-10

CONVERSION CABLE CT9920



Required to connect PW3390 to the current sensor with HIOKI PL14 on the output connector.

[Applicable products] CT7742, CT7642, CT7044, CT7045, CT7046

CONNECTION CABLE CT9904



Cable length: 1 m (3.28 ft) Required to connect the summing waveform output terminal of CT9557 to PW3390.

[Applicable products] CT9557

Voltage Measurement Options



VOLTAGE CORD L9438-50

banana-banana (red, black, 1 each), alligator clip, spiral tube, approx. 3 m (9.84 ft.) length

CAT IV 600 V, CAT III 1000 V



GRABBER CLIP L9243

GRABBER CLIP (red, black, 1 each) Attaches to the tip of the banana plug cable

CAT II 1000 V



VOLTAGE CORD L1000

banana-banana (red, yellow, blue, gray, 1 each, black × 4), alligator clip, approx. 3 m (9.84 ft.) length

CAT IV 600 V, CAT III 1000 V



PATCH CORD L1021-01

for branching voltage input, banana branch to banana clip (red × 1), 0.5 m (1.64 ft.) length CAT IV 600 V, CATIII 1000 V



EXTENSION CABLE SET L4931

banana-banana (red, black, 1 each), For extension of L9438-50 or L1000, approx. 3 m (9.84 ft.) length, With connector

CATIV600 V, CATIII1000 V



PATCH CORD L1021-01

for branching voltage input, banana branch to banana clip (black \times 1), 0.5 m (1.64 ft.) length

CAT IV600 V, CATIII 1000 V



WIRING ADAPTER PW9000

When making a 3-phase 3-wire (3P3W3M) connection, this product allows you to reduce the number of voltage cords from 6 to 3.

CATIV600 V, CATIII1000 V



WIRING ADAPTER PW9001

When making a 3-phase 4-wire (3P4W) connection, this product allows you to reduce the number of voltage cords from 6 to 4.

CATIV600 V, CATIII1000 V

Connection Options



CONNECTION CORD L9217

BNC-BNC. For motor analysis input Cable length: 1.6 m (5.25 ft) CATII600 V. CATIII300 V



LAN CABLE 9642

Supplied with straight to cross conversion connector, Cable length: 5 m (16.41 ft)



CONNECTION CABLE 9683

For synchronous measurement, Cable length: 1.5 m (4.92 ft)



RS-232C CABLE 9637

9pin-9pin cross Cable length: 1.8 m (5.91 ft)

Other Options



PC CARD 512MB 9728 PC CARD 1GB 9729 **PC CARD 2GB 9830**

Use only PC Cards sold by HIOKI. Compatibility and performance are not guaranteed for PC cards made by other manufacturers. You may be unable to read from or save data to such cards.



CARRYING CASE 9794

Carrying Case for PW3390 and 3390 448 mm (17.64 in) W x 618 mm (24.33 in) H x 295 mm (11.61 in) D

Built-To-Order (Other)

Please contact your Hioki distributor or subsidiary for more information.

D/A output cable D-sub 25-pin - BNC (male) Rackmount fittings (For EIA or JIS) PW9100A 5A-rated model

Rackmount fittings



For EIA or JIS

D/A output cable



D-sub 25-pin - BNC (male) 16 ch conversion, Cord length: 2.5 m (8.20 ft)

The Bluetooth word mark and logos are registered trademarks owned by Bluetooth SIG, Inc. and any use of such marks by H10K1 E.E. CORPORATION is under license. Note: Company names and Product names appearing in this catalog are trademarks or registered trademarks of various companies.

DISTRIBUTED BY



HEADQUARTERS

81 Koizumi. Ueda, Nagano 386-1192 Japan https://www.hioki.com/

